

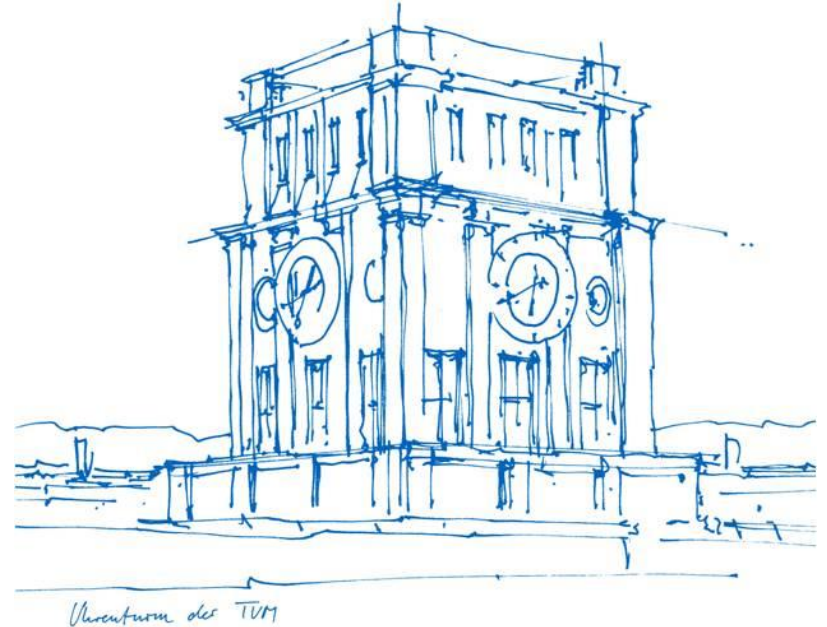
Learning from the Implicit Functional Hierarchy in an Analog Netlist

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Chair of Electronic Design Automation



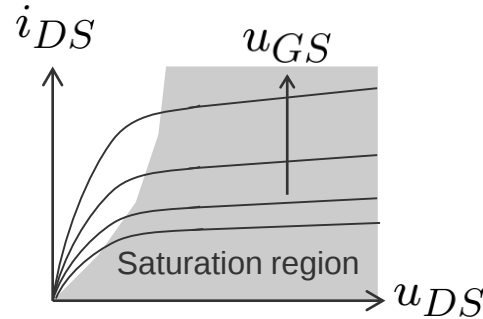
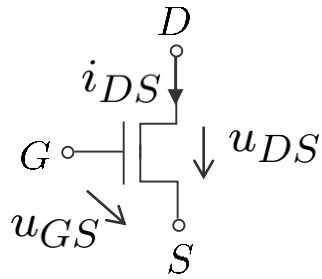
Content

- Constraints/rules from hierarchical structure (sizing)
- Constraints/rules from netlist and signal flow (placement) [slide 14, video minute 18:45]
- Constraints/rules/functions from hierarchical function (modeling) [slide 22, video minute 27:40]

Content

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Sizing Constraints – Transistor (1)



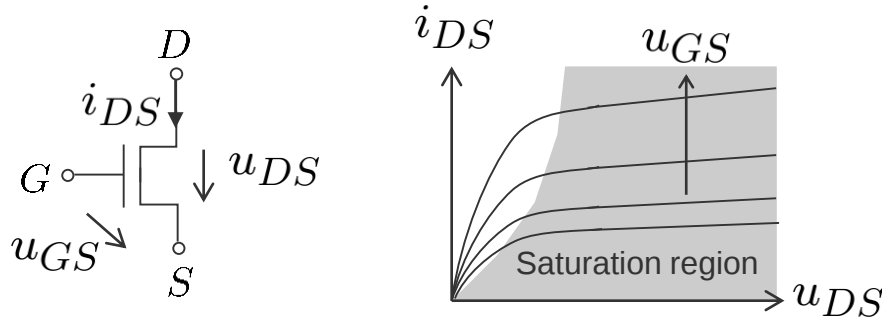
Voltage-controlled current source:

$$i_{DS} = K \cdot \frac{W}{L} \cdot (u_{GS} - U_{th})^2 \cdot (1 + \lambda \cdot u_{DS})$$

- Keep transistor in saturation:

$$u_{DS} - (u_{GS} - U_{th}) \geq U_{satmin} , \quad u_{GS} - U_{th} \geq 0 , \quad u_{DS} \geq 0$$

Sizing Constraints – Transistor (2)



Voltage-controlled current source:

$$i_{DS} = K \cdot \frac{W}{L} \cdot (u_{GS} - U_{th})^2 \cdot (1 + \lambda \cdot u_{DS})$$

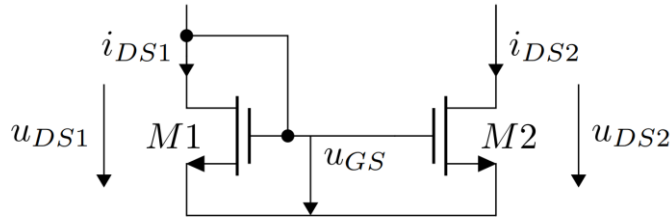
- Minimize variance of drain-source current due to manufacture variation:

$$\sigma_{i_{DS}}^2 = \sum_{X=K,W,L,U_{th}} \left(\frac{\partial i_{DS}}{\partial X} \right)^2 \cdot \sigma_X^2 \quad \longrightarrow \quad \frac{\sigma_{i_{DS}}^2}{i_{DS}^2} = \frac{A_K}{W \cdot L} + \frac{\sigma_W^2}{W^2} + \frac{\sigma_L^2}{L^2} + \frac{4}{(u_{GS} - U_{th})^2} \cdot \frac{A_{U_{th}}}{W \cdot L}$$

$$\left(\frac{\sigma_K}{K} \right)^2 = \frac{A_K}{W \cdot L} \quad \sigma_{V_{th}}^2 = \frac{A_{V_{th}}}{W \cdot L}$$

$$W \cdot L \geq A_{minA}, \quad W \geq W_{minA}, \quad L \geq L_{minA}$$

Sizing Constraints – Current Mirror



$$r = \frac{i_{DS2}}{i_{DS1}} = \frac{\frac{W_2}{L_2} \cdot (u_{GS} - U_{th2})^2 \cdot (1 + \lambda \cdot u_{DS2})}{\frac{W_1}{L_1} \cdot (u_{GS} - U_{th1})^2 \cdot (1 + \lambda \cdot u_{DS1})}$$

- Prepare regular layout (fingers, interdigitated/common centroid):
- Reduce impact of local manufacturing variation:
- Reduce impact of channel length modulation in circuit:

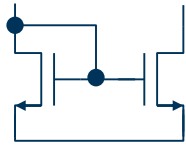
$$L_1 = L_2, \quad W_2 = r \cdot W_1$$

$$\|u_{GS} - U_{th1,2}\| \geq U_{GSmin}$$

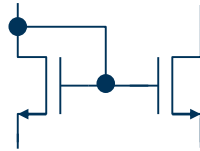
$$\|u_{DS2} - U_{DS1}\| \leq \Delta U_{DSmax}$$

Structural Blocks – Transistor Pairs

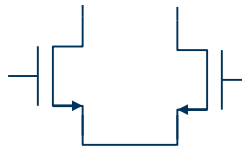
- 203 variants (Bell number)
- Few transistor pairs with design-relevant function, e.g.,



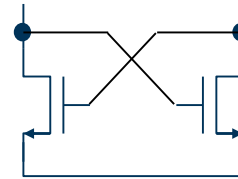
2-transistor
current mirror



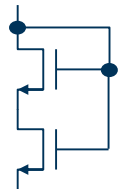
Level shifter



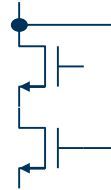
Differential pair



Flipflop



Voltage
reference 1



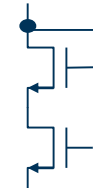
Voltage
reference 2



Current mirror
load



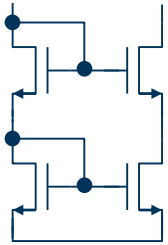
Cascode
pair



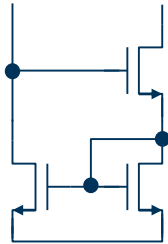
Mixed
pair

Structural Blocks – Transistor Groups

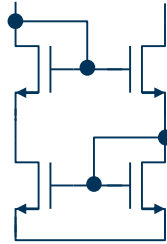
- E.g., current mirrors with 3 or 4 transistors, differential stage,



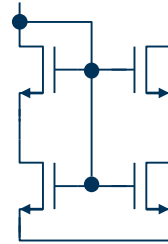
Cascode
current
mirror (cm)



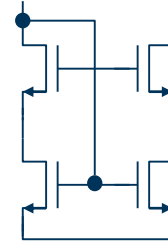
Wilson
cm



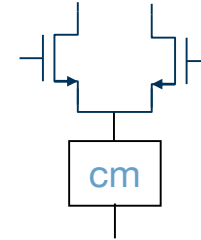
Wilson 2
cm



4-transistor
cm



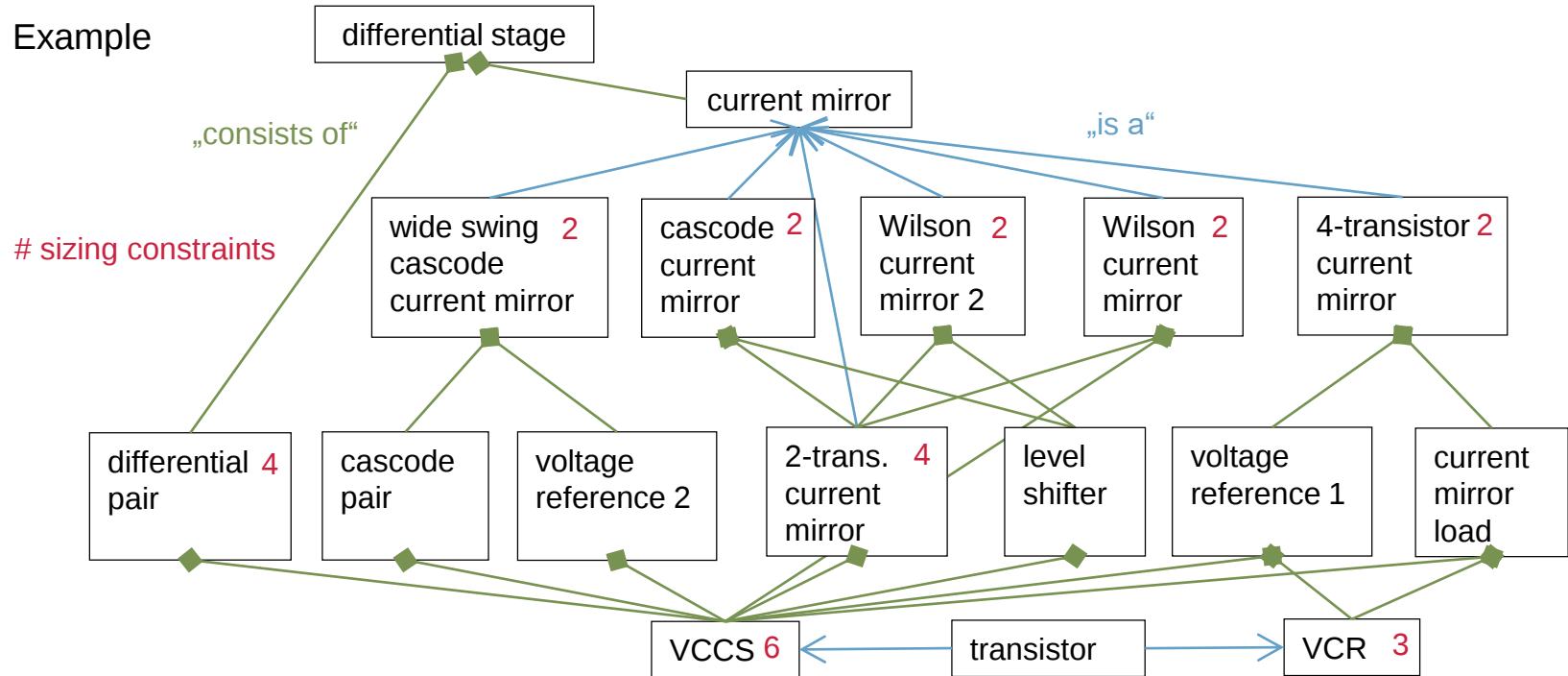
Wide-swing
cascode cm



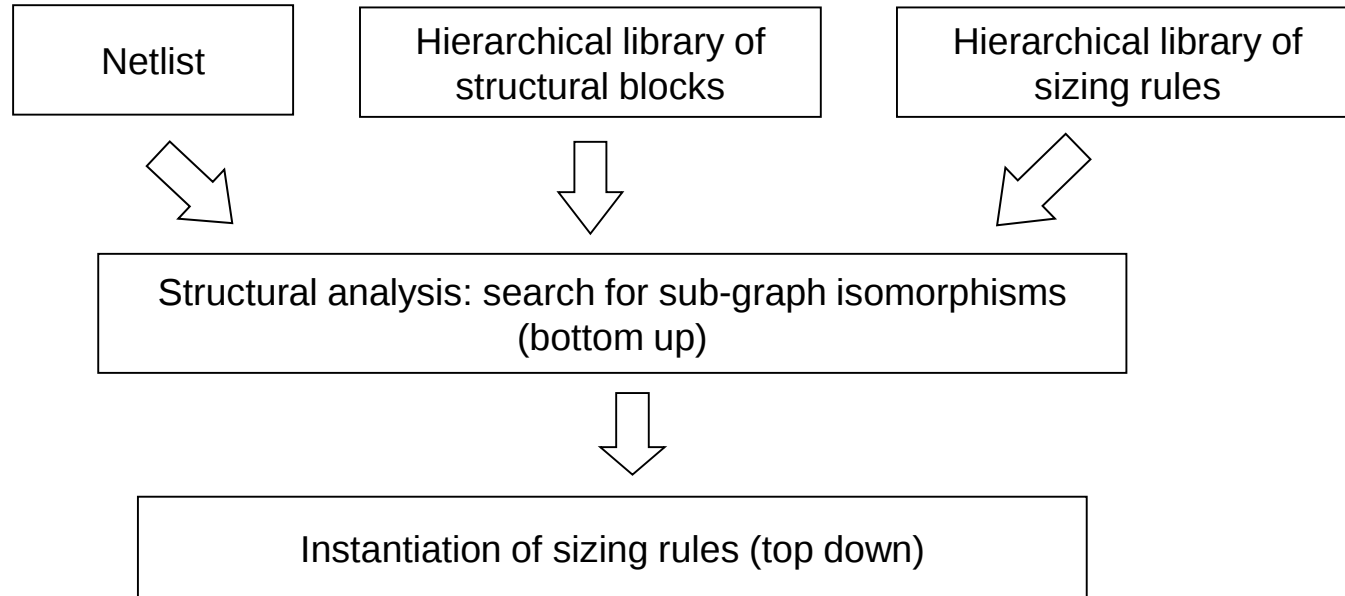
Differential
stage

Hierarchical Library of Structural Blocks

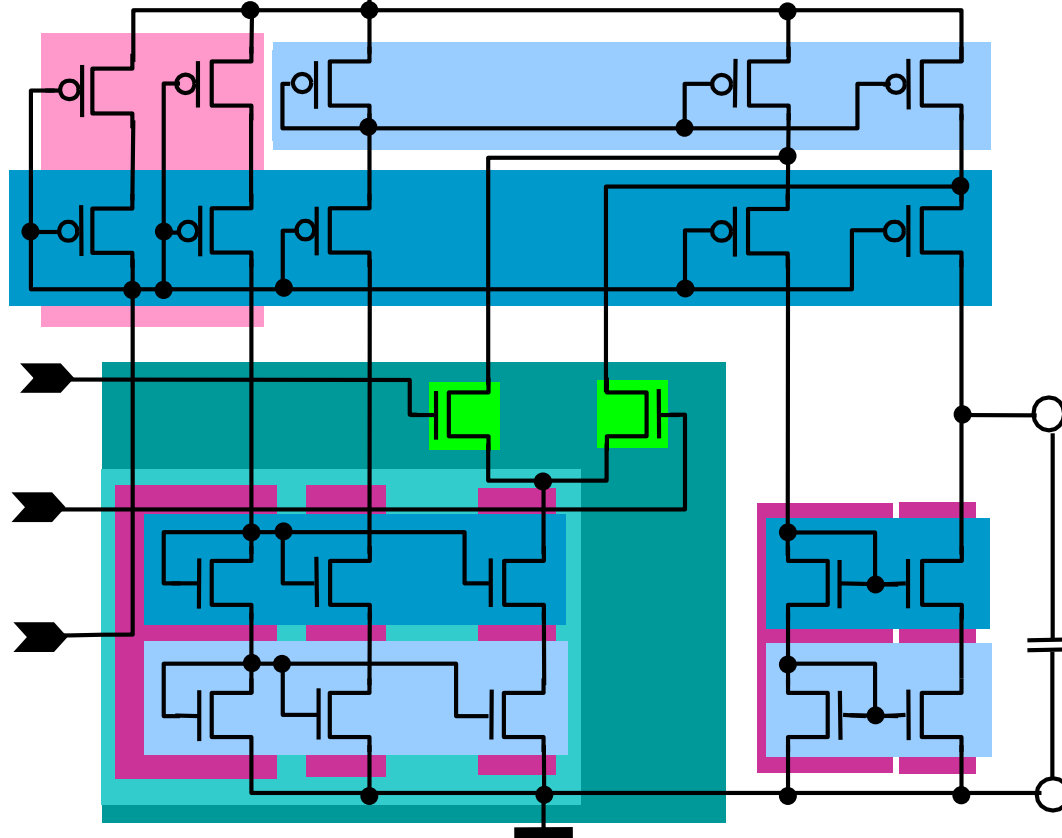
- Example



Structural Analysis of a Netlist



Structural Analysis – Example



- voltage reference 1
- current mirror load
- 2-trans. current mirror
- level shifter
- differential pair

4-transistor current mirror

current mirror (bank)

level shifter (bank)

cascode current mirror

casc. curr. mirror bank

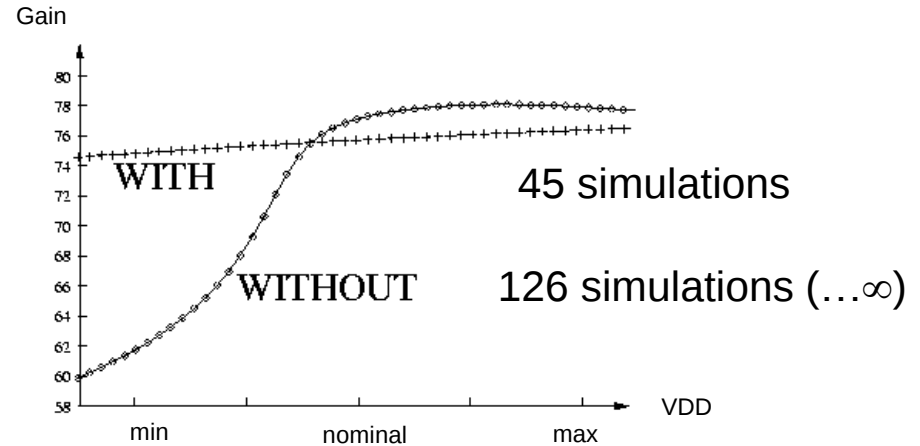
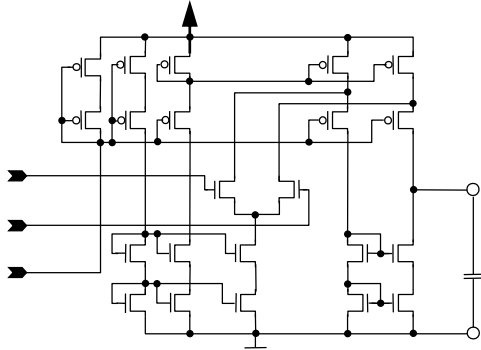
differential stage

30 equations + 160 inequalities → 190 sizing rules



Influence of Sizing Constraints on Sizing Process

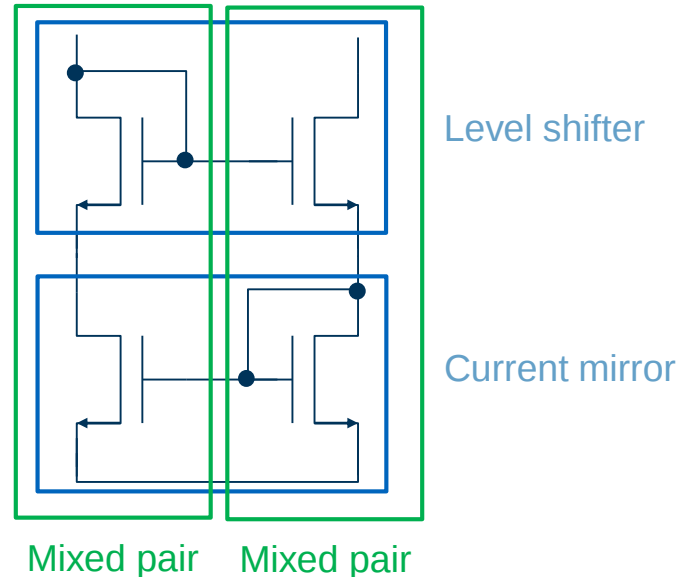
- Typical example



- Better efficiency and convergence of sizing process
- Higher circuit robustness

It Is Not That Easy

- Arbitration of transistor groups: “If a transistor is part of group A, it is not part of group B.”
- Several ways of composition, e.g., Wilson 2 current mirror:

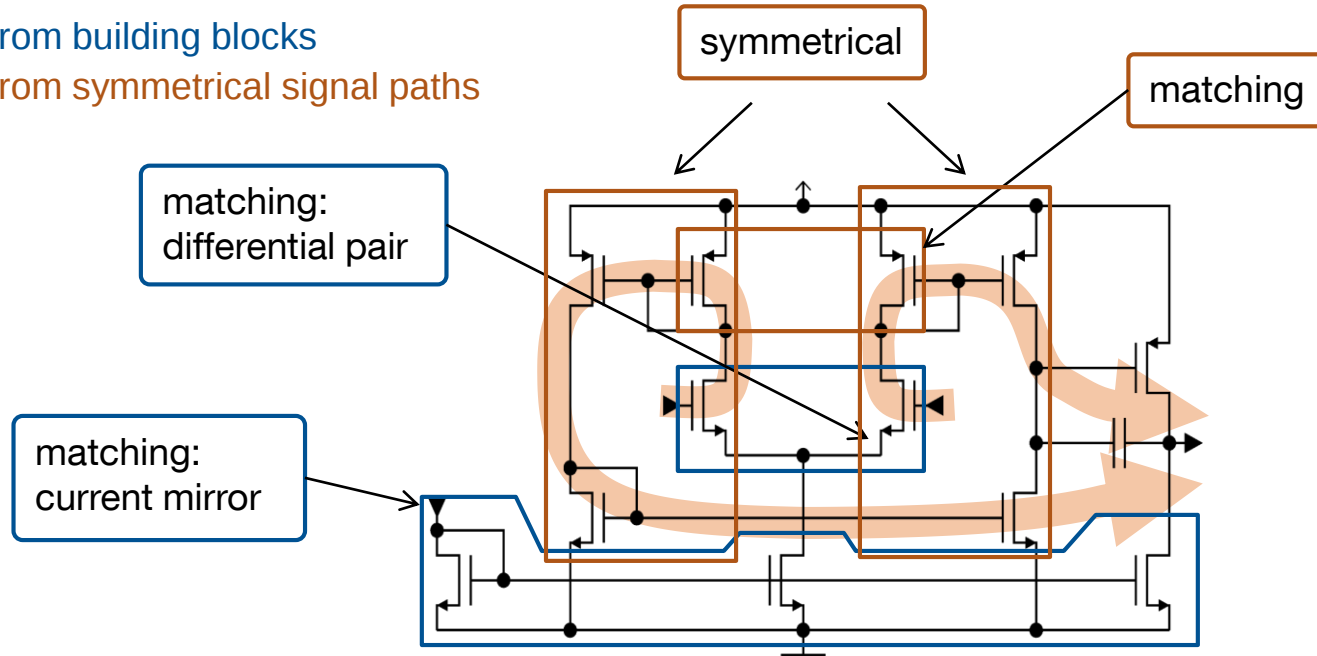


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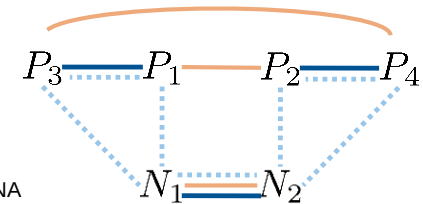
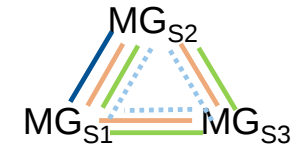
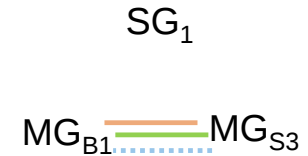
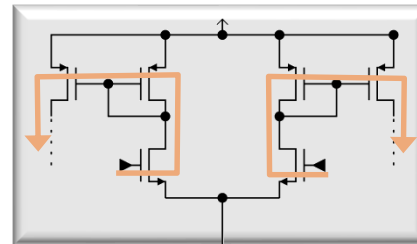
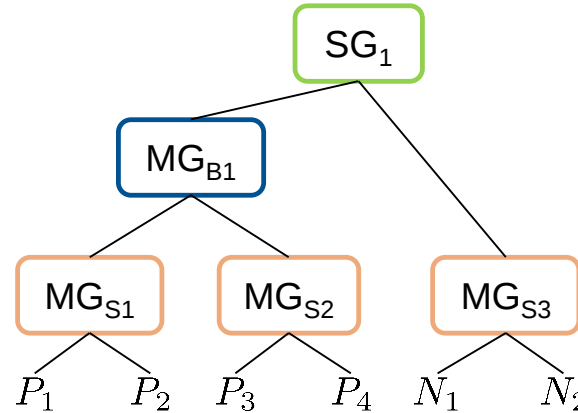
Constraints Across Building Blocks

- Constraints from building blocks
- Constraints from symmetrical signal paths



Placement Plan Construction from Constraint Hierarchy

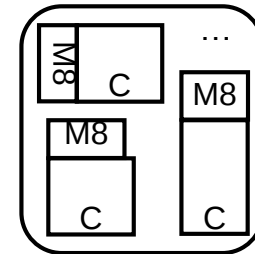
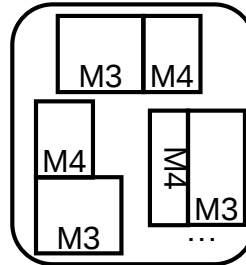
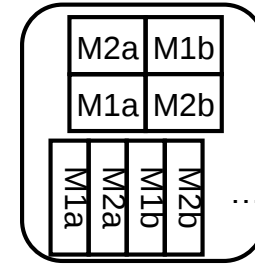
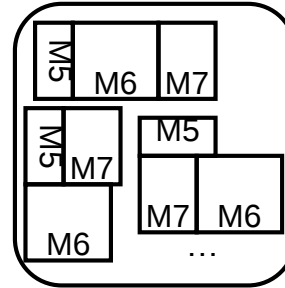
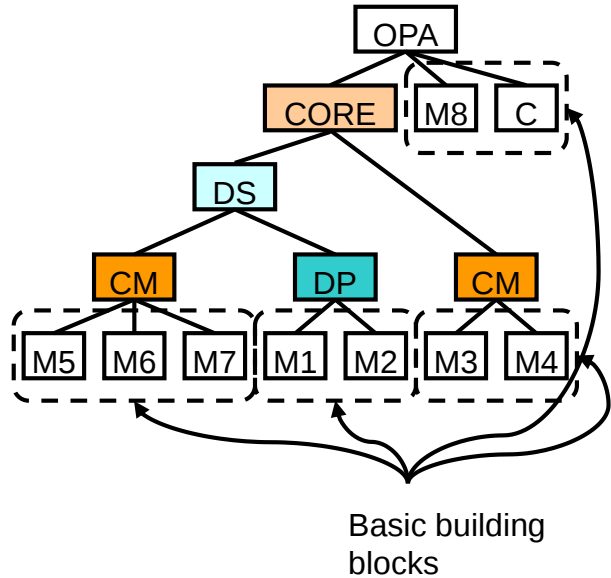
- Priority:
 1. Matching constraints — (symmetry path)
 2. Matching constraints — (building blocks)
 3. Proximity constraints (building blocks)
 4. Symmetry constraints —
 5. Proximity constraints (netlist)
- $MG_{S/B}$: Matching group (symmetry/building blocks)
- SG: Symmetry group
- PG_N : Proximity group (netlist)



3.: NA
4.: fully meshed

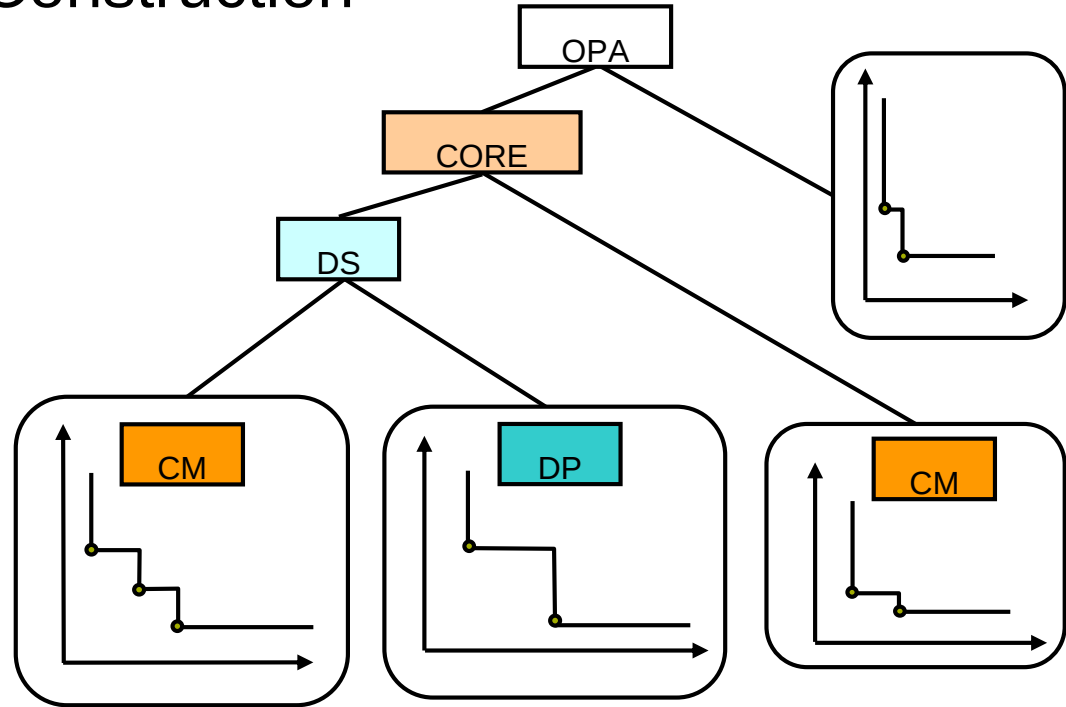


Placement: Enumerate Basic Building Blocks



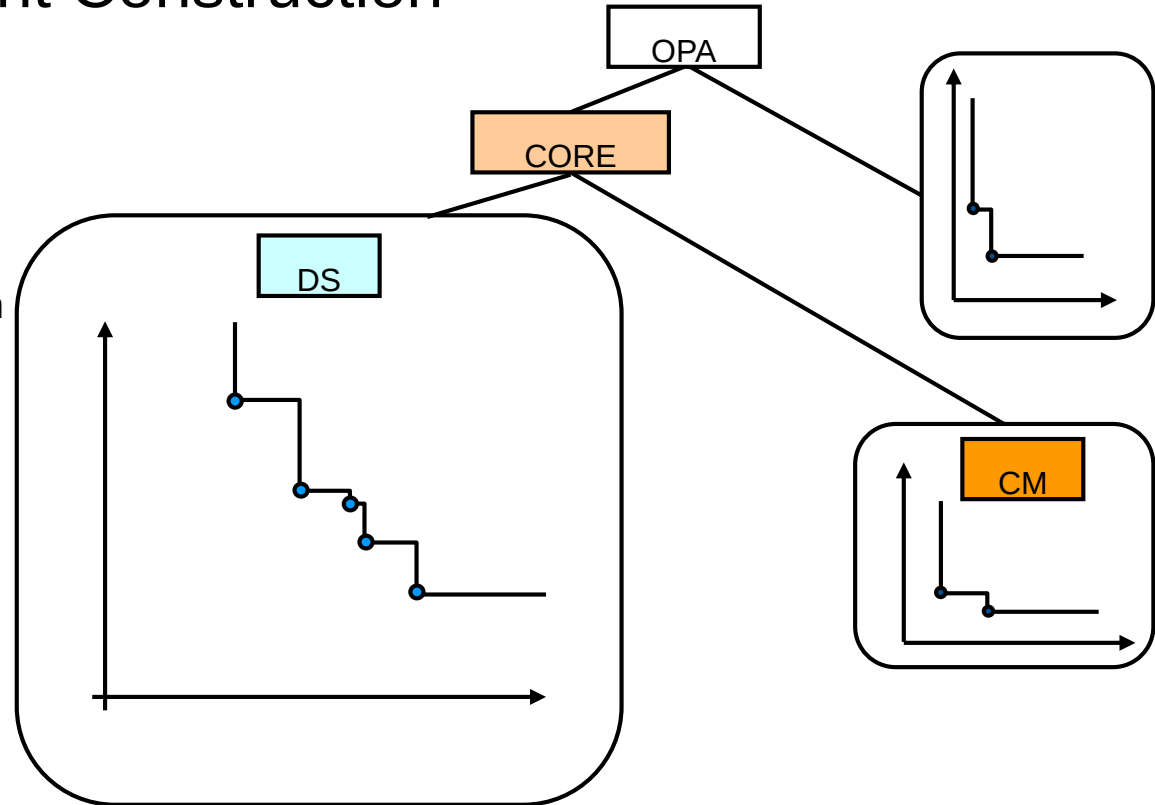
Bottom-up Placement Construction

- Code placements as B* trees in enhanced shape functions
- Enhanced shape functions are added horizontally/vertically
- Bottom up along placement plan
- White space is utilized
- Constraints are provably kept



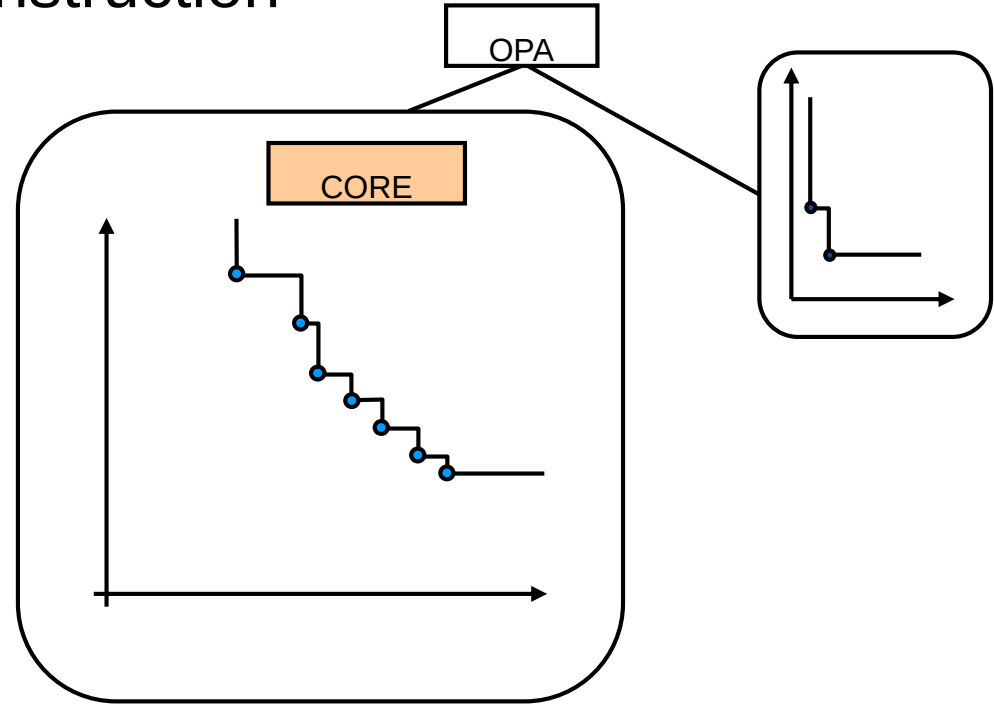
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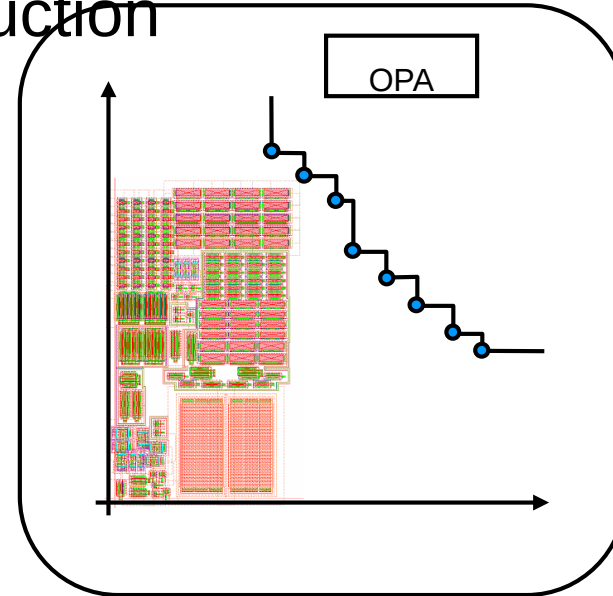
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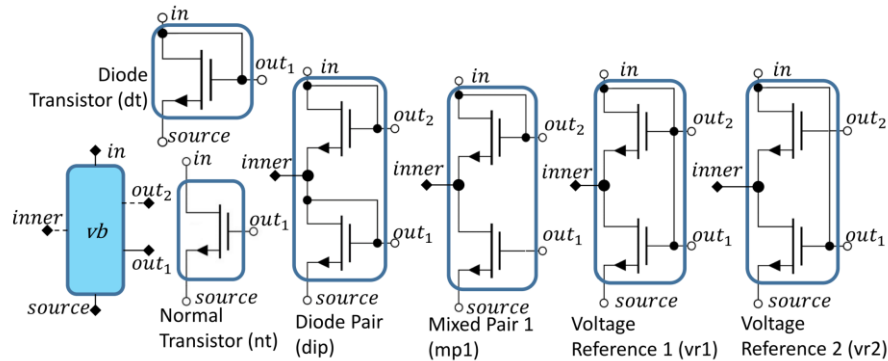
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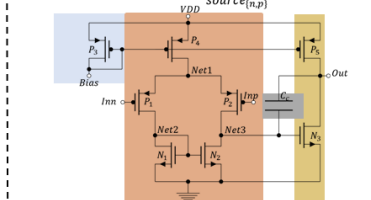
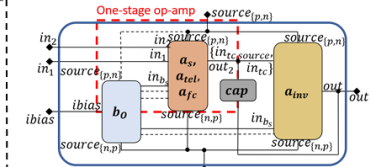
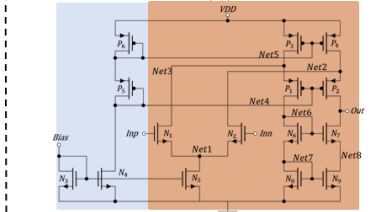
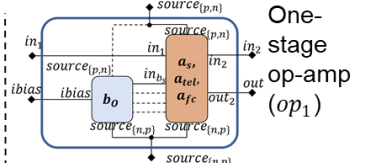
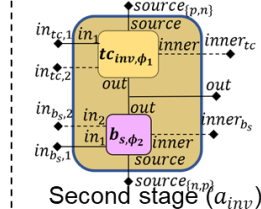
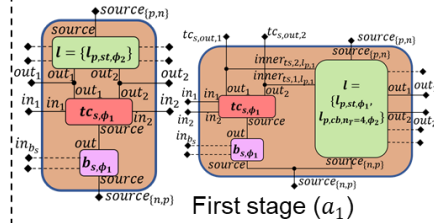
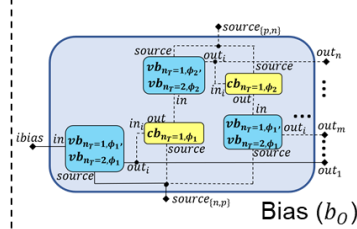
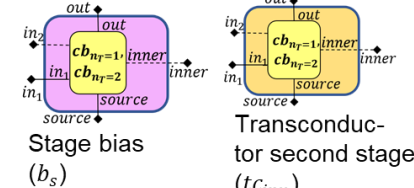
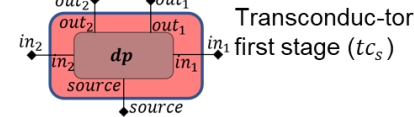
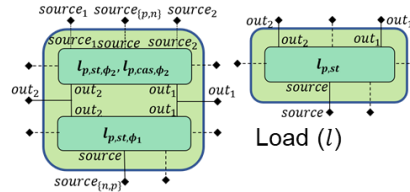
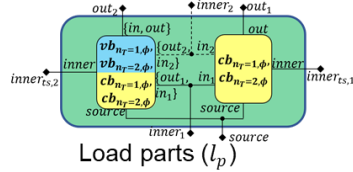
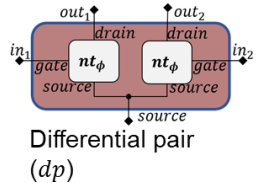
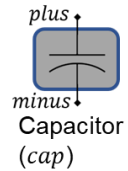
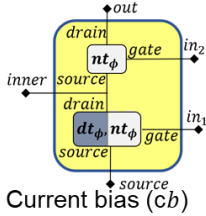
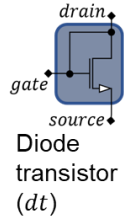
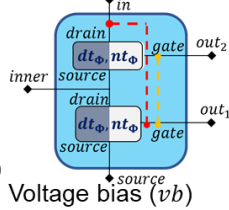
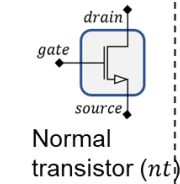
Beyond Structural Blocks: Functional Blocks



- Blocks representing a certain analog function within analog circuit
- Number of pins may vary depending on structural implementation by transistor netlist
- One functional block refers to several structural implementations
- One structural implementation refers to several functional blocks

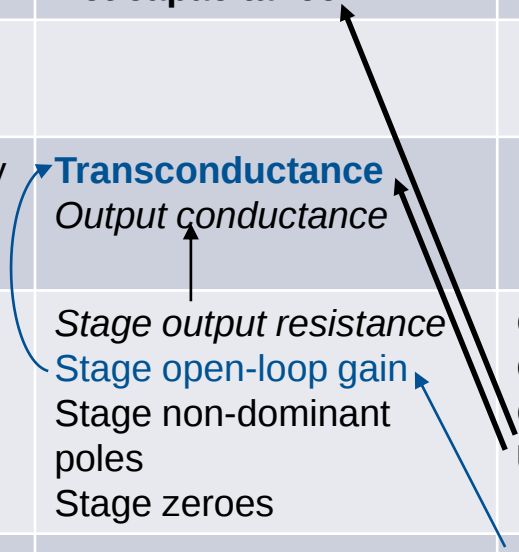
- Example voltage bias (vb)
- Converts current into node *in* into voltage at node *out1* or at nodes *out1* and *out2*
- E.g., part of current mirror

Functional Block Library



Hierarchical Performance and Constraint Library

	Symmetry constraints	Behavioral constraints	Intermediate performance equations	Op-amp performance equations
Devices			Saturation vds Net capacitance	Area Quiescent power
Structures	Current mirror constraints	Current mirror behavior		
Amplification stage subblocks	Load Non-inverting transconductor	Complementary transconductor	Transconductance <i>Output conductance</i>	
Amplification stages	Inverting stages	Output voltage offset	<i>Stage output resistance</i> Stage open-loop gain Stage non-dominant poles Stage zeroes	Common-mode input voltage Output voltage Common-mode rejection ratio Unity-gain bandwidth
Op-amp			Dominant pole Positive zero	Open-loop gain Slew rate Phase margin



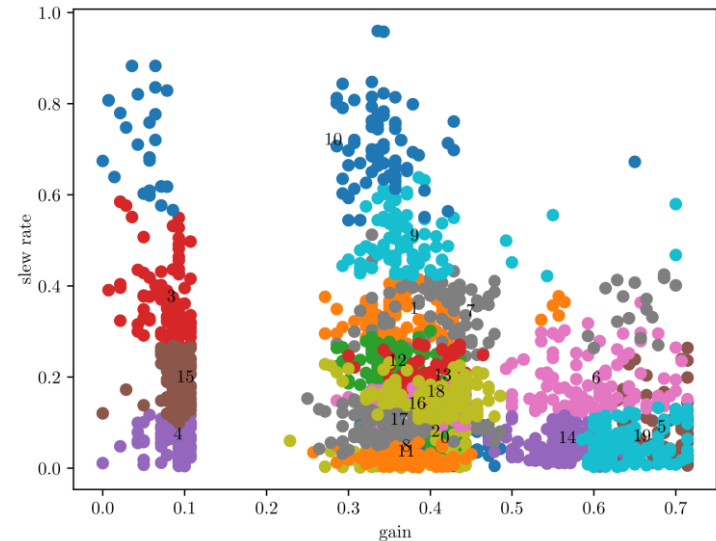
Design – Clustering and Modeling with Neural Networks

Performance	Minimum	Maximum
<i>gain</i>	40 dB	140 dB
<i>slew rate</i>	$2 \frac{V}{\mu s}$	$217 \frac{V}{\mu s}$
<i>phase margin</i>	55°	90°
<i>transit frequency</i>	3 MHz	173 MHz

- >500 opamp structures
- ~20 different structural building blocks : transistor pairs, current mirror types, analog inverters
- Functional block characterization: load, transconductance, bias, opamp stage
- >150 sizings for various specs for each opamp structure
- Overall ~100,000 designs with these details: structure, hierarchy of building blocks, functional blocks, sizing, performance

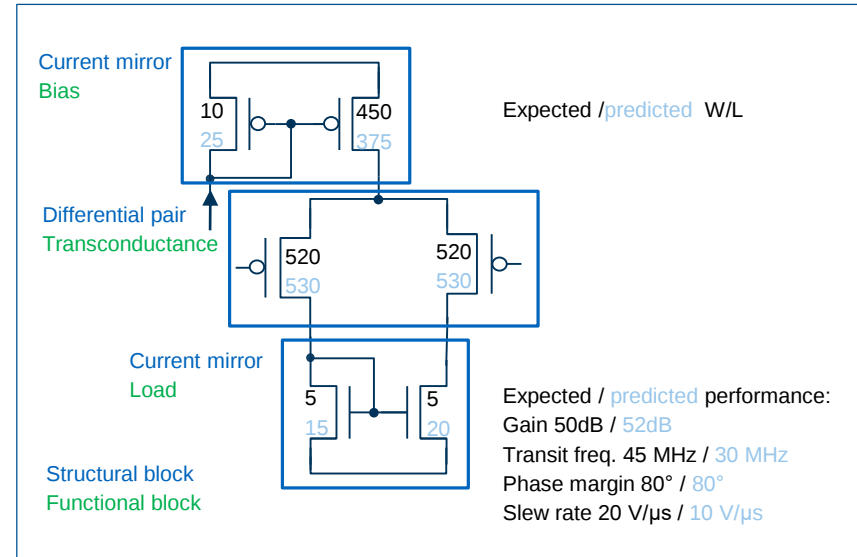
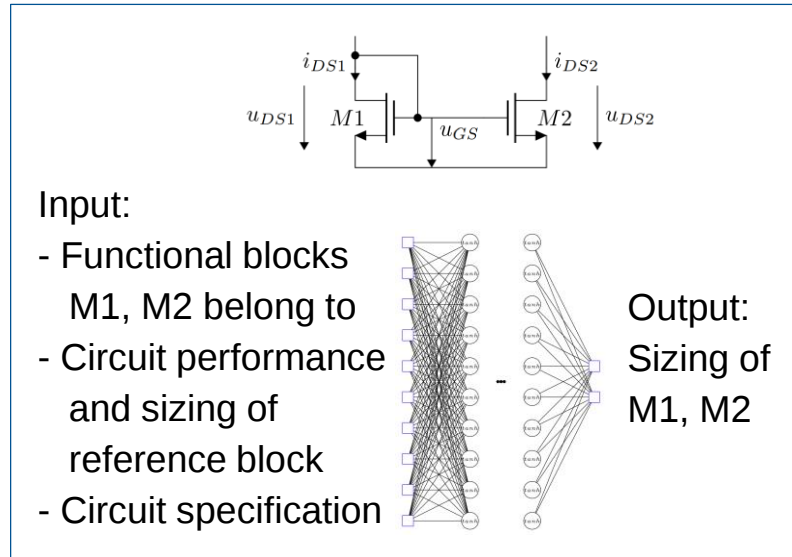
Neural-network Driven Topology Selection

- Build neural network, e.g., for ~20 clusters of performance subranges, mapping performance on topology
- Speed up topology selection by applying this neural network (reduced set of potential topologies compared to enumeration)
- Precision > 70%, recall > 70%



Neural-network Driven Circuit Sizing

- Determine a neural network for each functional block that maps circuit specification on sizing of block
- Independent sizing of functional blocks of a circuit, e.g.,



Conclusion

- Hierarchical libraries of building blocks
- Associated generic sets of constraints, rules and functions
- Set-up of constraints, rules and functions crucial for synthesis, sizing and layout

Thanks to TUM Contributors to Constraint Methods

- Maximilian Neuner*
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- Michael Zwerger
- Michael Eick
- Martin Strasser
- Tobias Massier
- Robert Schwencker
- Stephan Zizala
- Josef Eckmüller

(ordering according to (*expected) PhD graduation starting from most recent)

References

Structural analysis

- (1) Helmut Graeb. 2020. Mathematical Methods of Circuit Design. <https://mediatum.ub.tum.de/doc/1086708/1086708.pdf>.
- (2) Helmut Graeb, Stephan Zizala, Josef Eckmueller, Kurt Antreich. 2001. The sizing rules method for analog integrated circuit design. *ACM/IEEE Int. Conf. Computer-Aided Design (ICCAD)*, <https://ieeexplore.ieee.org/document/968645>.
- (3) Tobias Massier, Helmut Graeb, Ulf Schlichtmann. 2008. The Sizing Rules Method for CMOS and Bipolar Analog Integrated Circuit Synthesis. *IEEE Trans. Computer-Aided Design (TCAD)*, <https://ieeexplore.ieee.org/document/4670074>.
- (4) M. Eick, H. Graeb, Towards Automatic Structural Analysis of Mixed-Signal Circuits, In: Analog/RF and Mixed-Signal Circuit Systematic Design, M. Fakhfakh, E. Tlelo-Cuautle, R. Castro-Lopez (Eds.), Springer, 2013. https://link.springer.com/chapter/10.1007/978-3-642-36329-0_1

Sizing

- (1) Robert Schwencker, Josef Eckmueller, Helmut Graeb, Kurt Antreich. 1999. Automating the sizing of analog CMOS circuits by consideration of structural constraints. *Design, Automation and Test in Europe Conference*, <https://ieeexplore.ieee.org/document/761141>.
- (2) M. Eick, H. Graeb, MARS: Matching-driven analog sizing, *IEEE Transactions on Computer-Aided Design of Integrated Circuits (TCAD)*, 2012. <https://ieeexplore.ieee.org/document/6238393>

Layout

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