

From Electronic Design Automation to Automotive Design Automation

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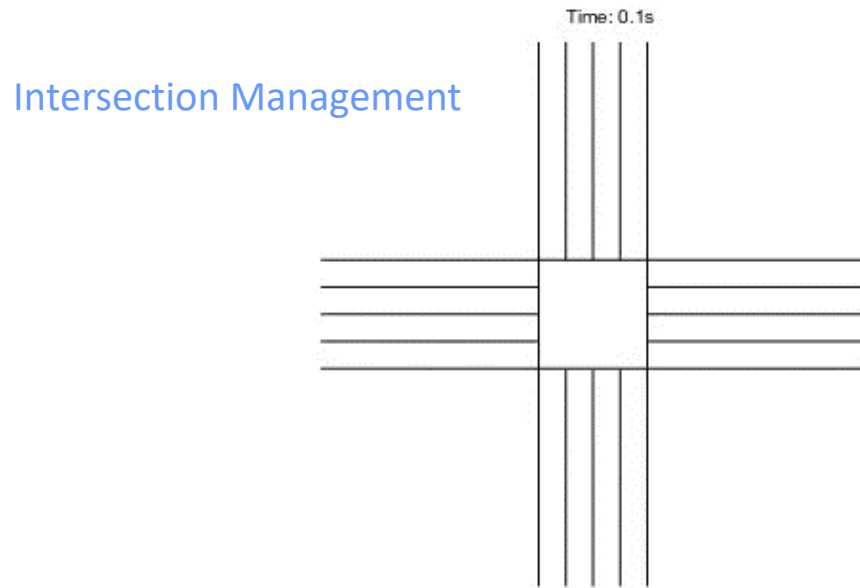
CSIE Department

National Taiwan University

April 2019

Connected and Autonomous Vehicles

- ❑ A good application may need both of "connectivity" and "autonomy"

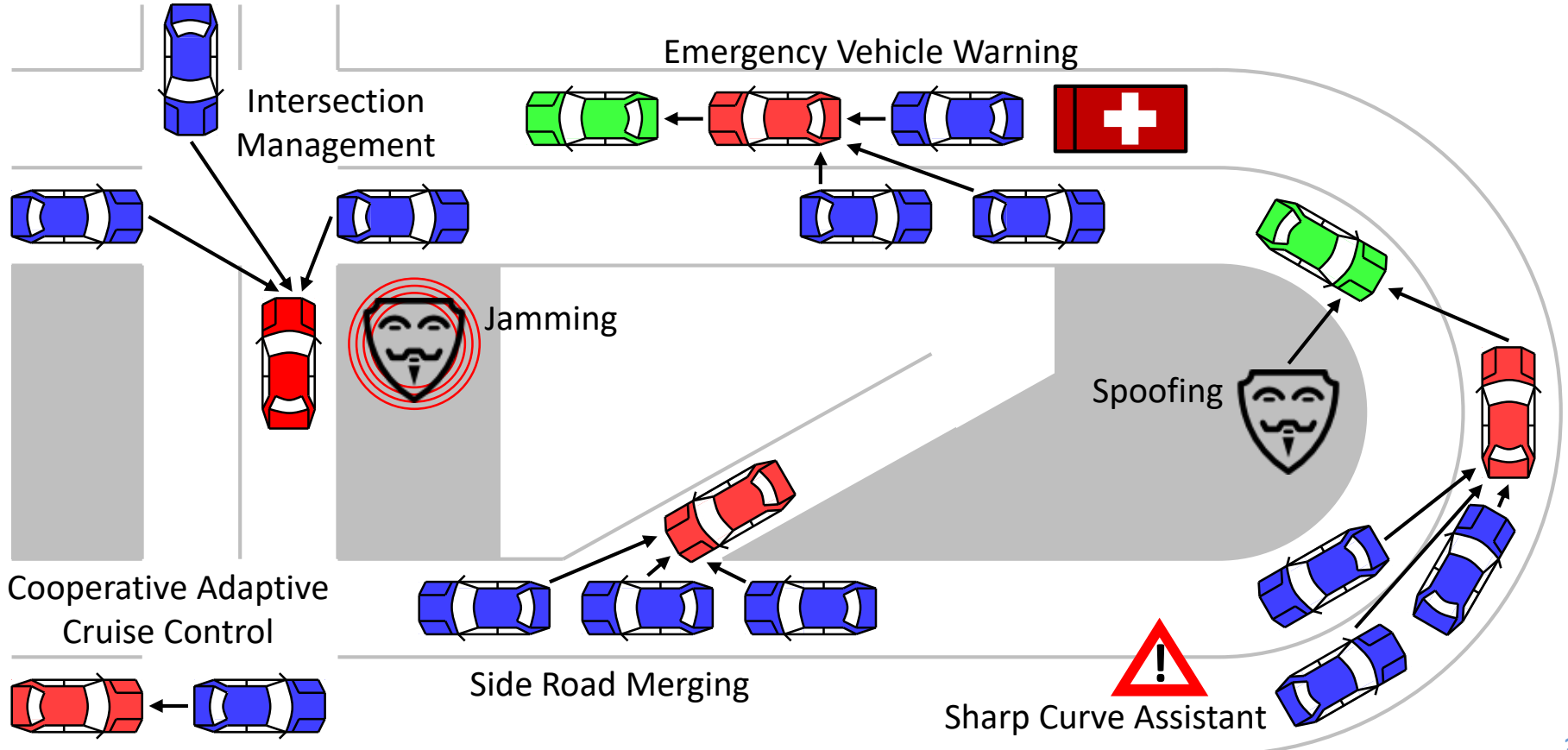


- What if the intersection management does not have connectivity?
- What if the intersection management does not have autonomy?

Connected Applications

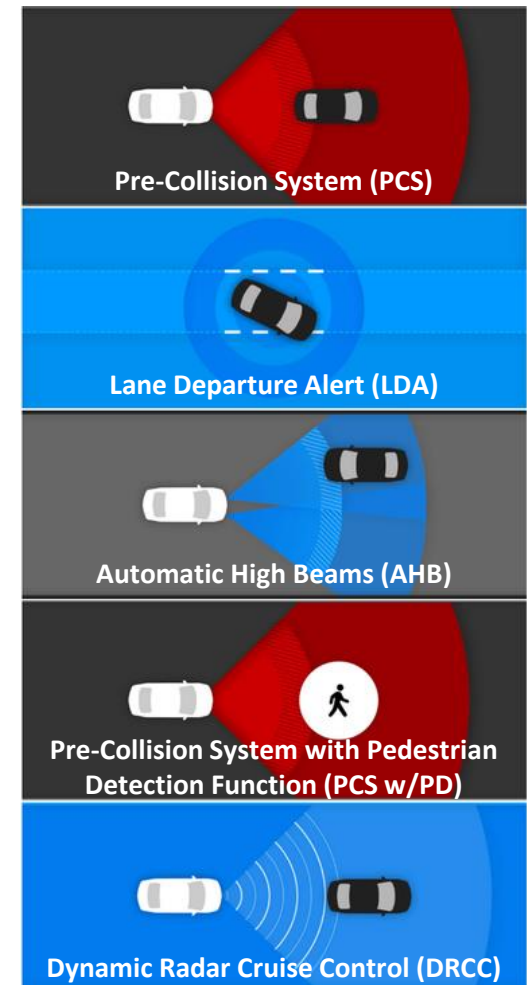
□ Connectivity realizes more applications, together with

- ADAS
- Autonomous functions



Software Design Complexity

- ❑ Various applications including Advanced Driver Assistance Systems (ADAS) and autonomous functions
- ❑ Various software programs for sensing, signal processing, control, decision making, etc.
 - Embedded software value to vehicle's total value
 - 2% → 13% from 2000 to 2010
 - Number of lines of code
 - 1 → 10+ → 100 million from 2000 → 2010 → now
- ❑ Due to the safety-critical nature, correctness and quality of software are extremely important



Hardware Design Complexity

❑ Number of Electronic Control Units (ECUs)

- 20 → 50+ in the past decade

❑ Integrated architecture

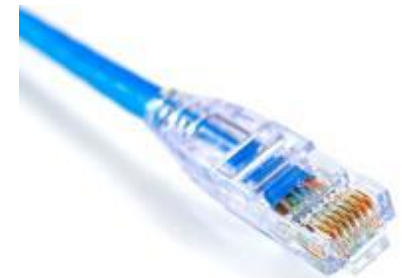
- One function can be distributed over multiple ECUs, and multiple functions can be supported by one ECU
 - More sharing and contention among software functions
 - Traditional federated architecture: each function is deployed to one ECU and provided as a black-box by its supplier

❑ New computational components

- Field Programmable Gate Array (FPGA)
- Graphical Processing Unit (GPU)

❑ Next-generation communication protocols

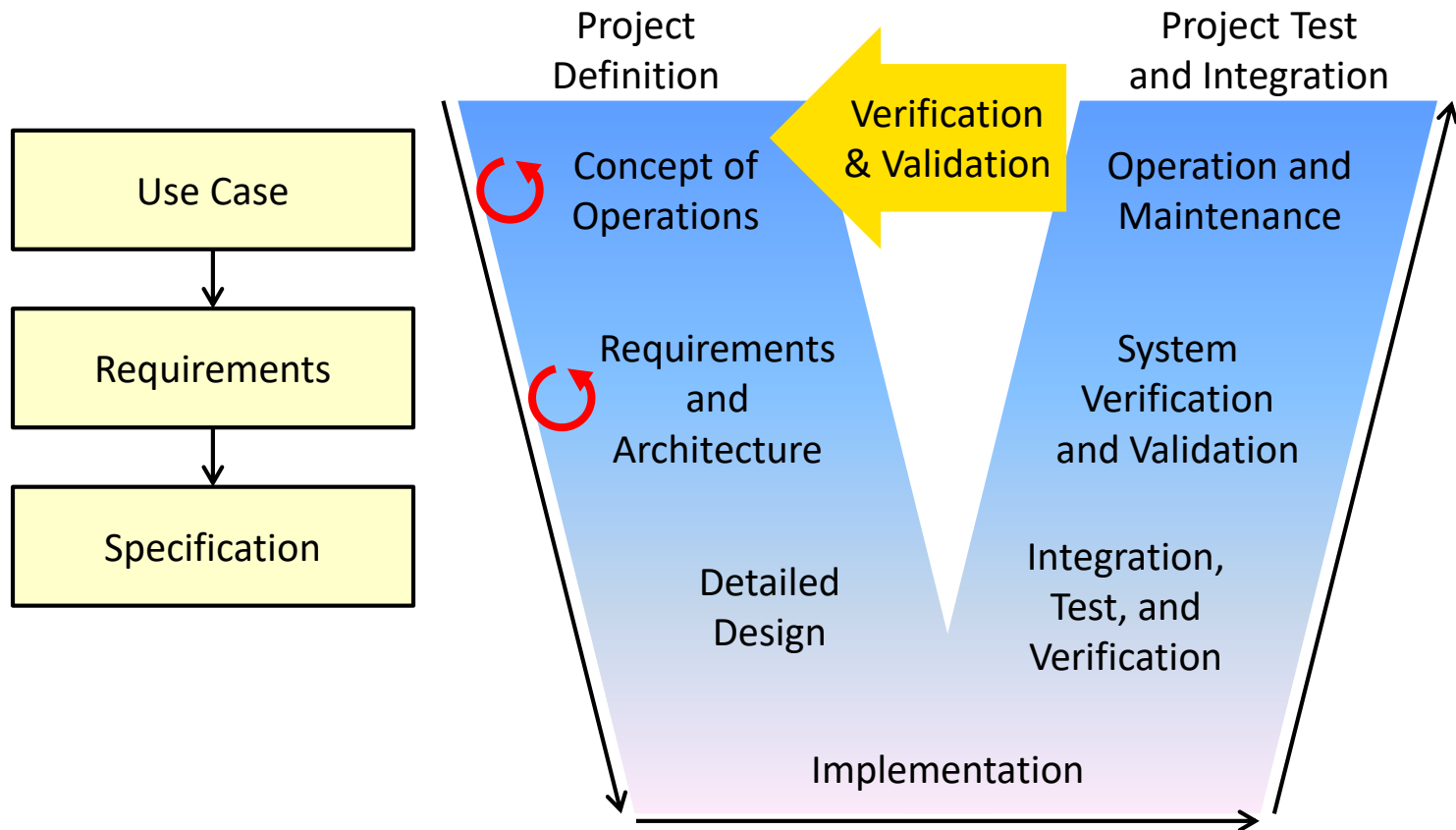
- Ethernet-based protocols



<https://en.wikipedia.org/wiki/Ethernet>

"Design Automation"

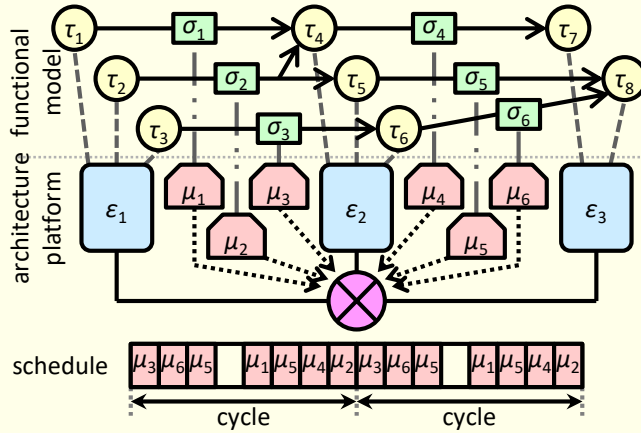
- ❑ Consider different design metrics
 - Safety, reliability, robustness, performance, etc.
- ❑ Assist system designers for early design decisions



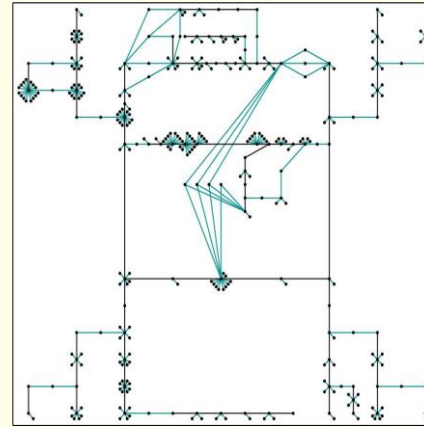
EDA vs. Automotive Design Automation

Automotive Design

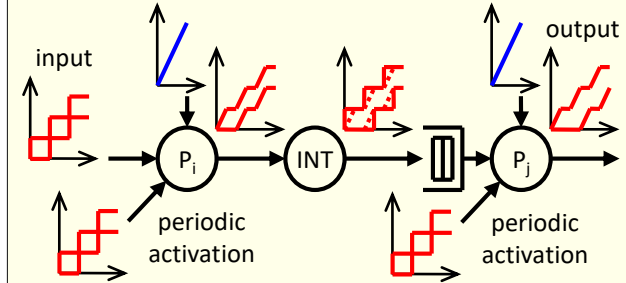
Modeling



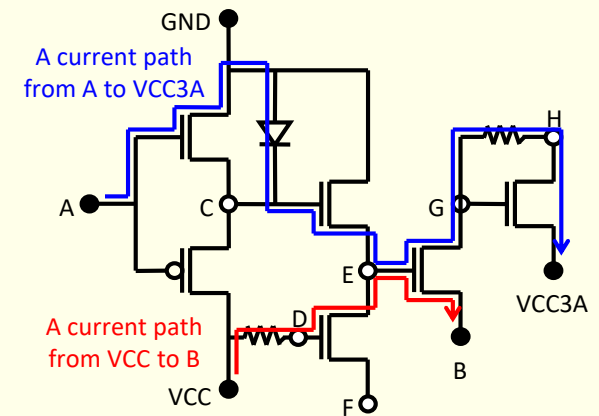
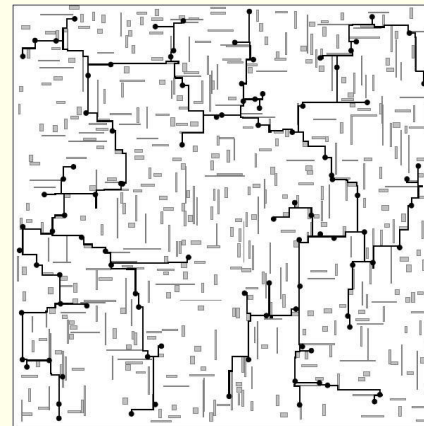
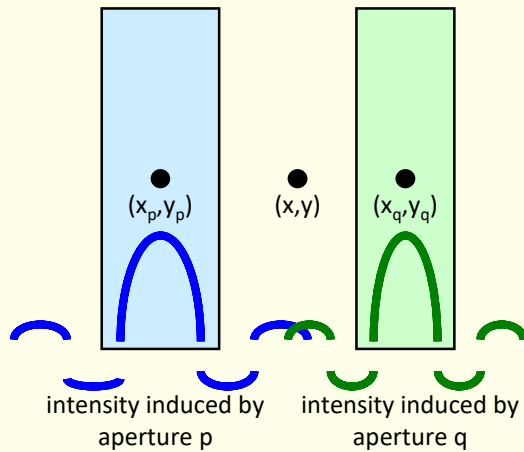
Design



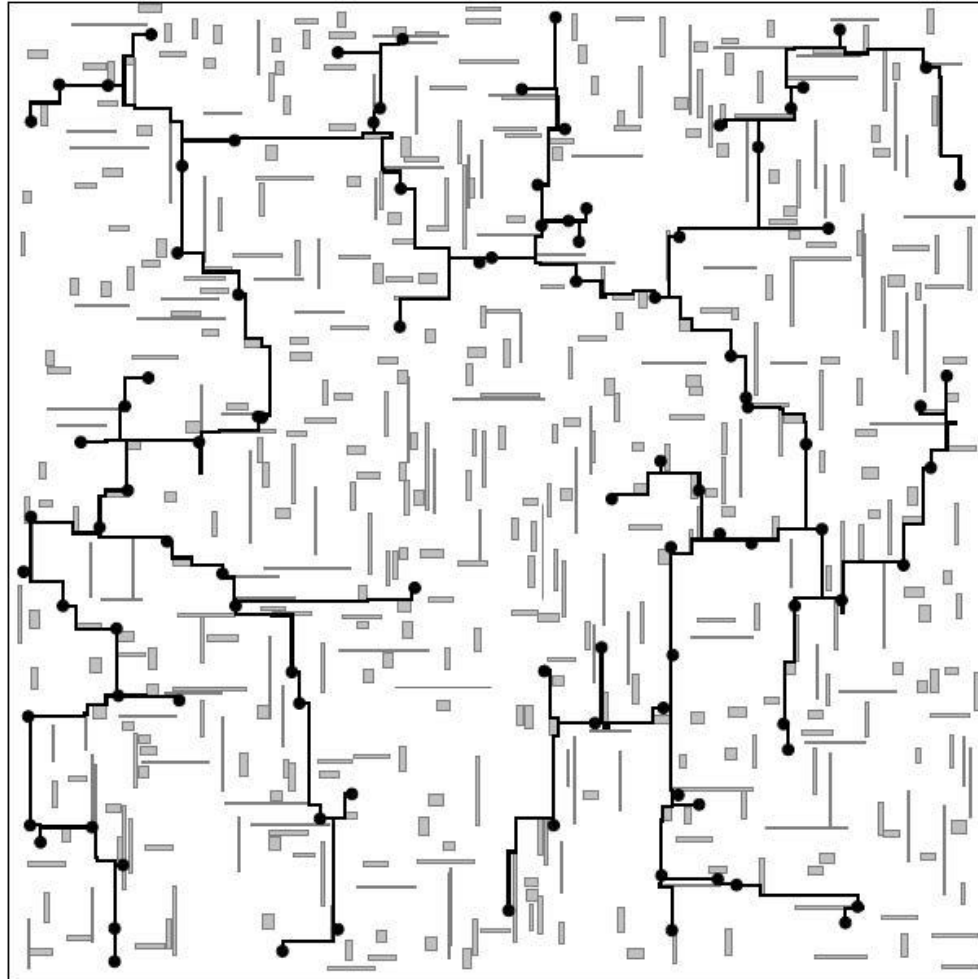
Analysis



Electronic Design Automation (EDA)



EDA: Wire Routing and Wire Sizing



Similar Problem in Automotive Design

❑ The wiring weight of a system can be up to 30kg

➤ The third heaviest and costliest component in an automotive system (after the chassis and the engine)

➤ Netlist ○ ○ ○

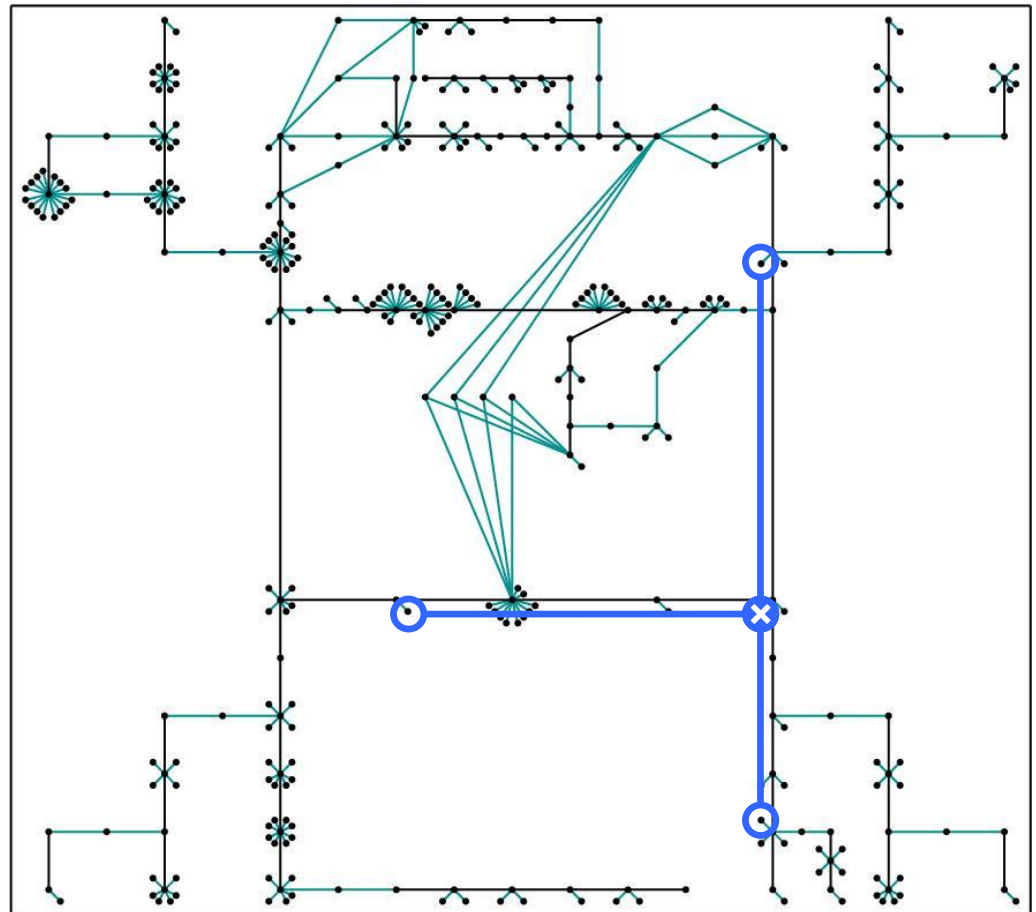
- A set of "parts" to be connected

➤ Splice ✕

- Used for connecting more than two wires
- Steiner vertex!

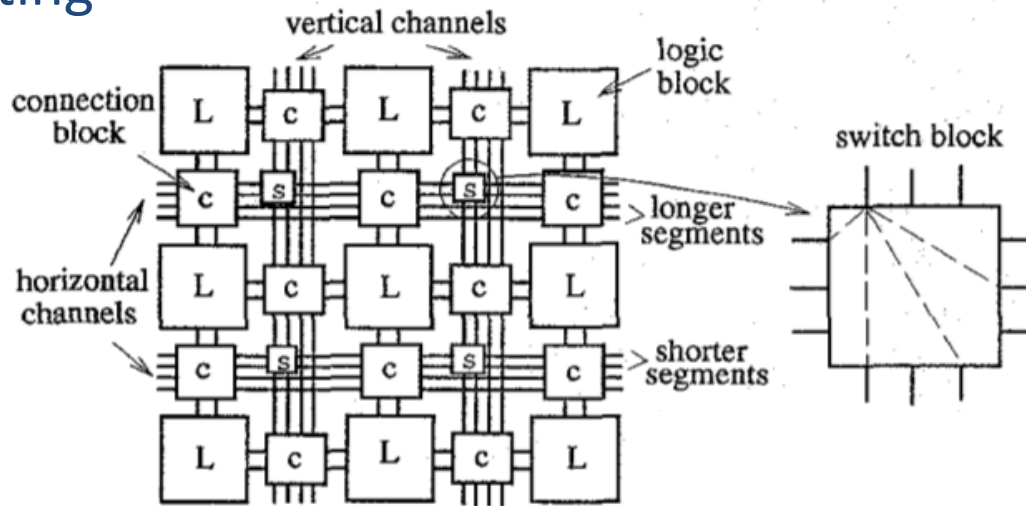
➤ Where to put splices?

- Steiner tree problem

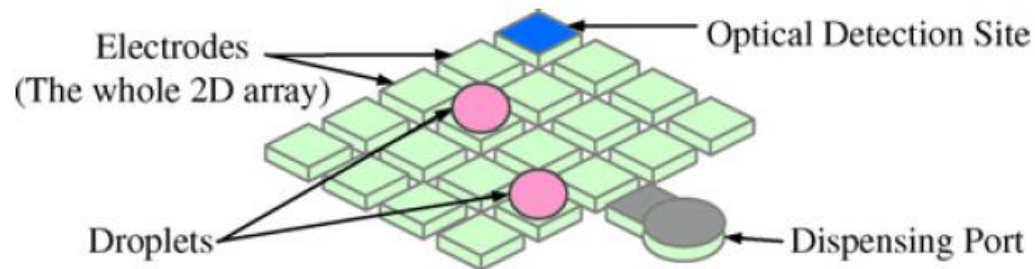


EDA: FPGA and Bio-Chip Routing

□ FPGA routing



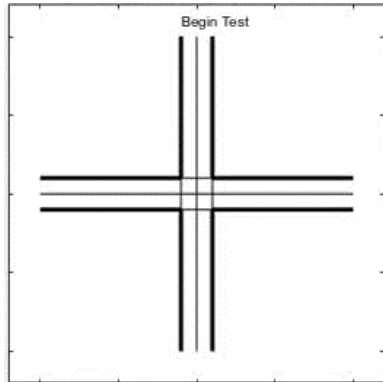
□ Bio-chip routing



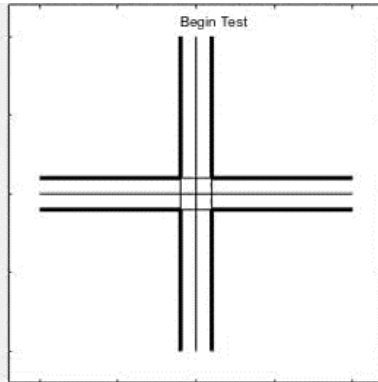
- Chang et al., "FPGA global routing based on a new congestion metric," ICCAD 1995.
- Lin and Chang, "Cross-contamination aware design methodology for pin-constrained digital microfluidic biochips," DAC 2010.

Similar Problem in Automotive Design

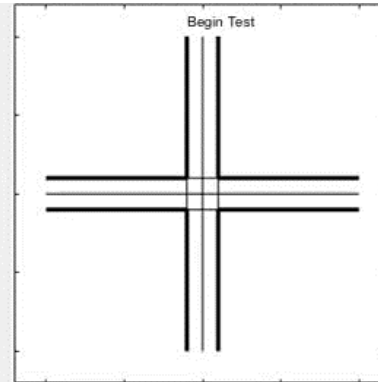
No Traffic Light +
No Communication



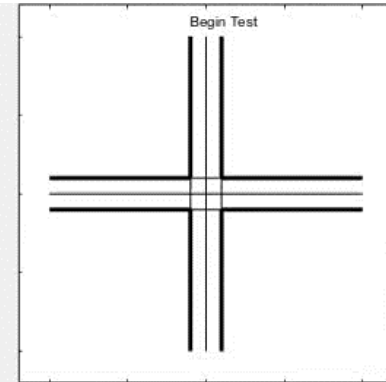
Traffic Light 5s



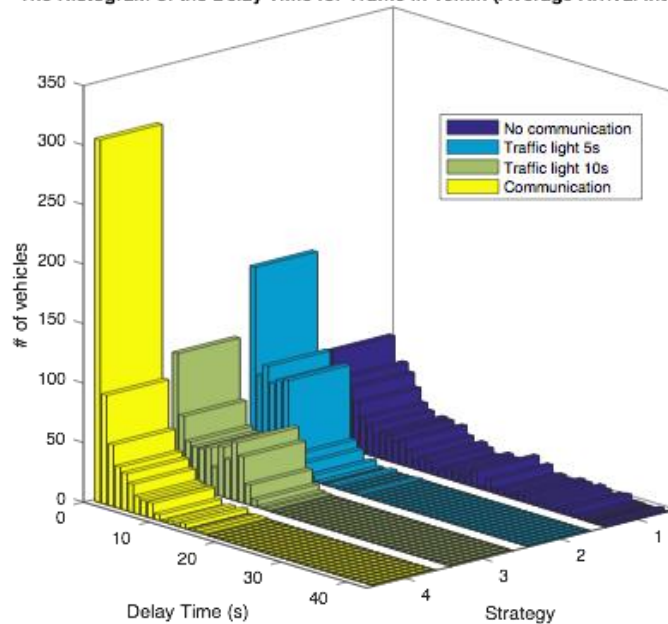
Traffic Light 10s



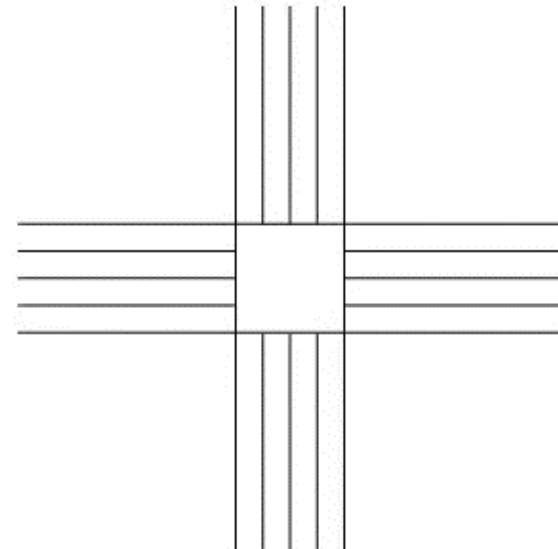
No Traffic Light
+ Communication



The Histogram of the Delay Time for Traffic in 10min (Average Arrival Interval 4s)



Extension to Multiple Lanes

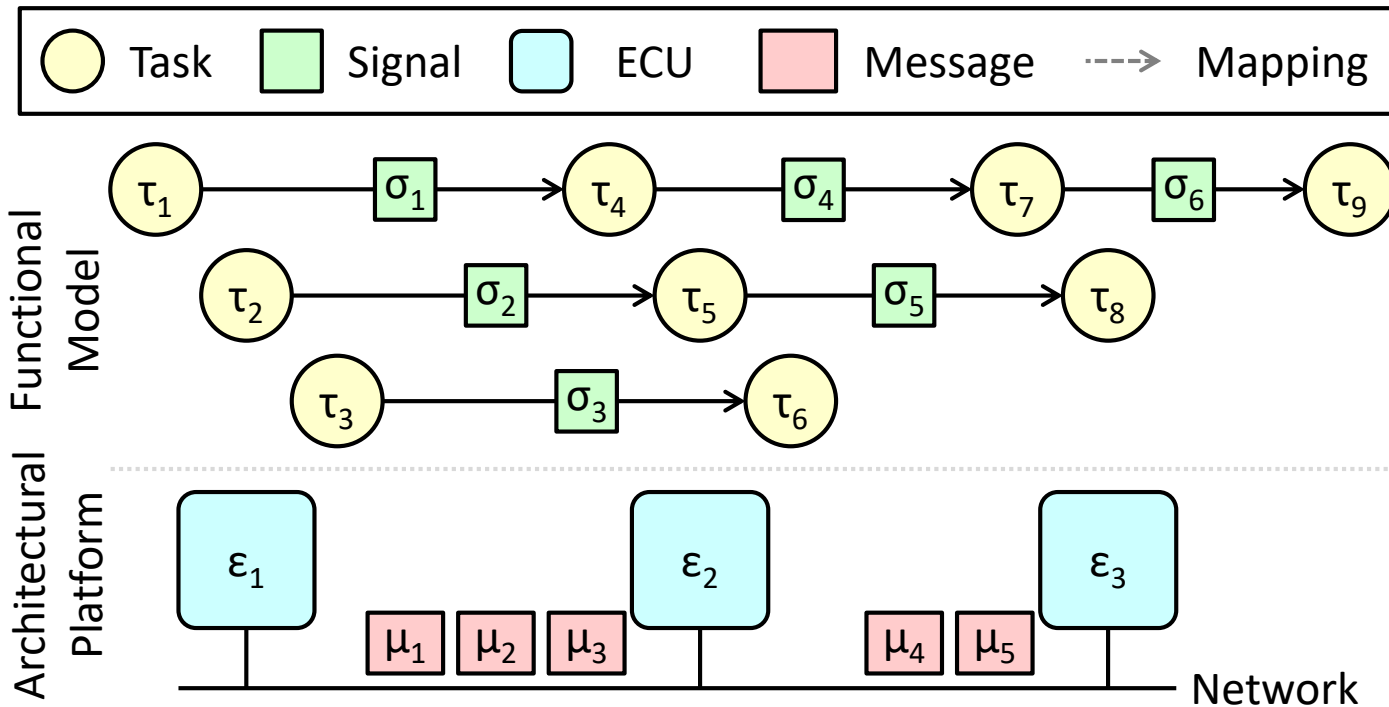


Outline

<p><u>#1</u> Placement</p>	<p><u>#2</u> Verification</p>
<p><u>#3</u> Software Integrity</p>	<p><u>#4</u> Security-Aware Design and Analysis</p>

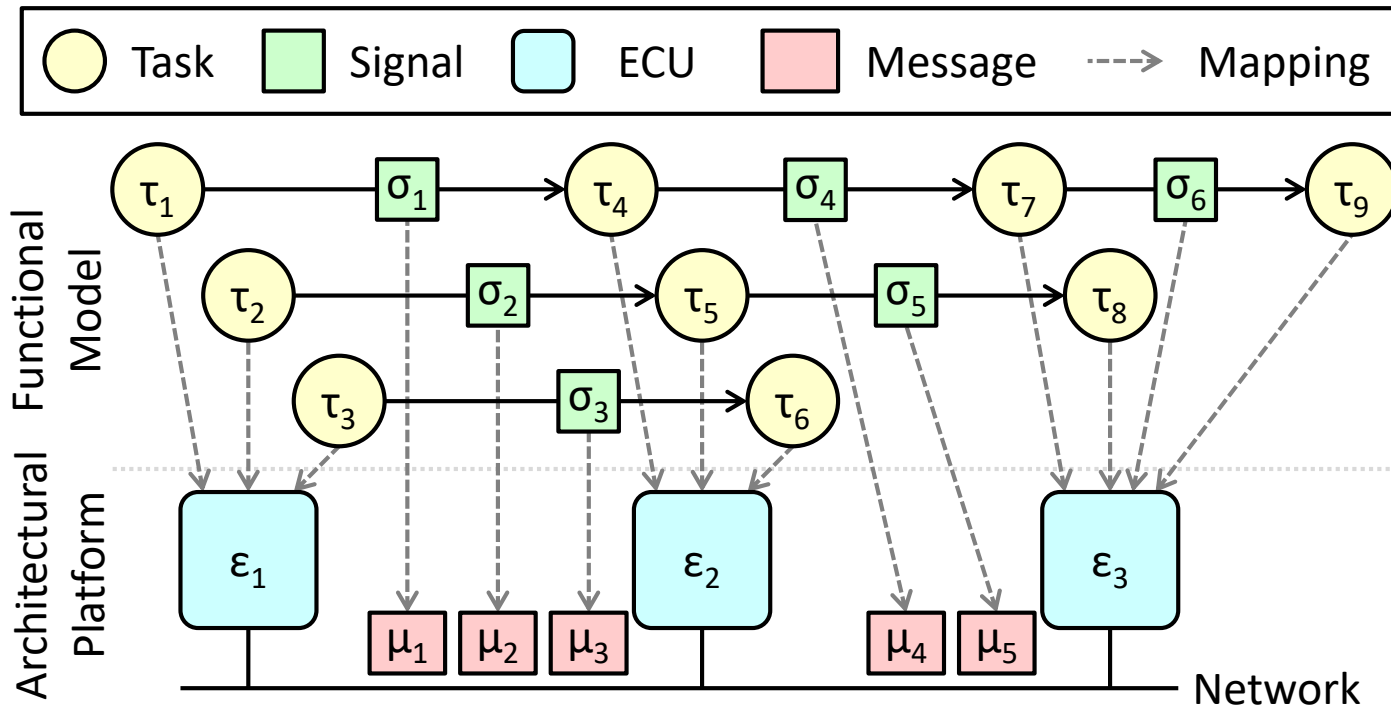
One Example Formulation

- ❑ Software (functional model): task graph
- ❑ Hardware (architectural platform): distributed Electronic Control Units (ECUs) connected by a network

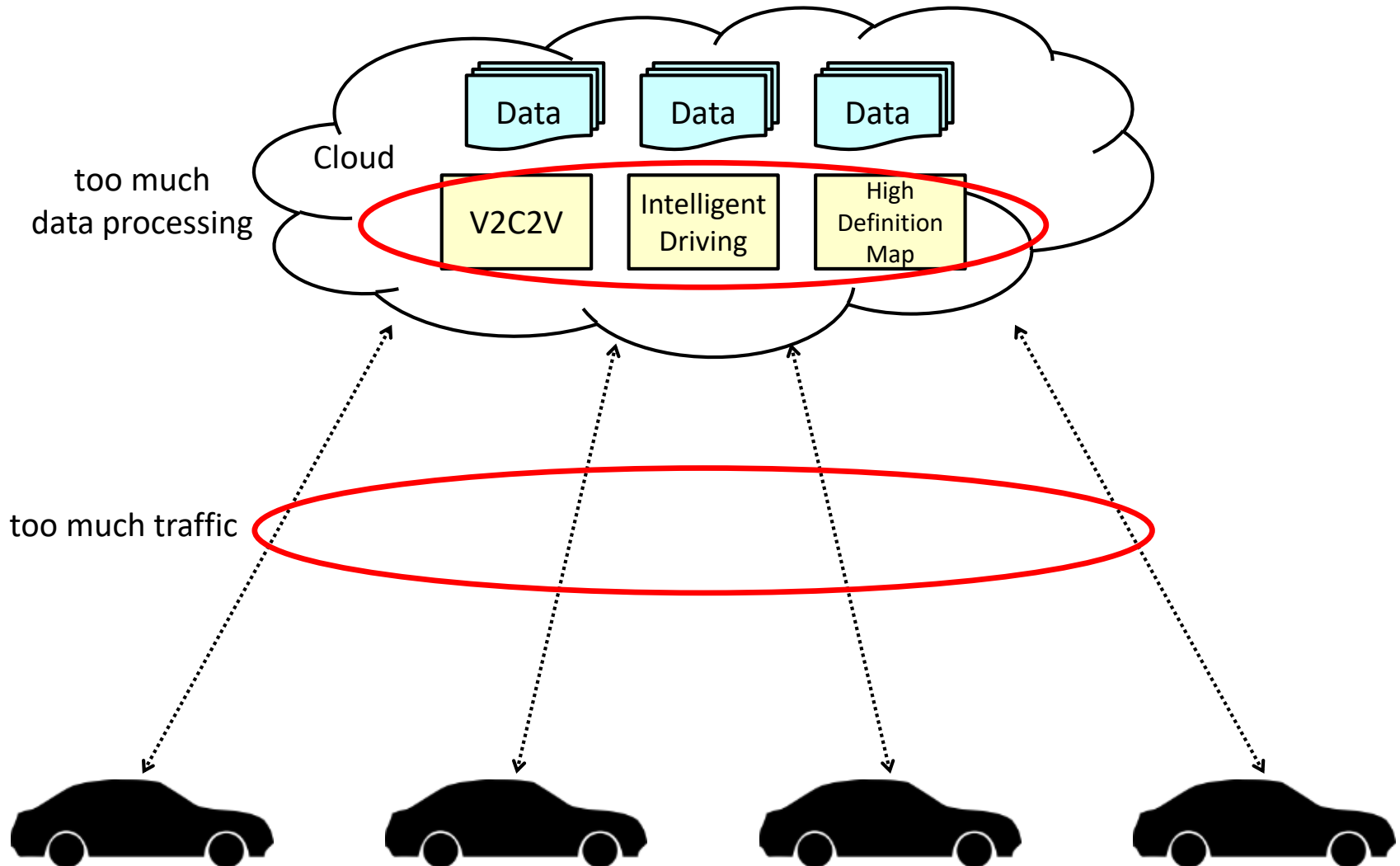


One Example Solution

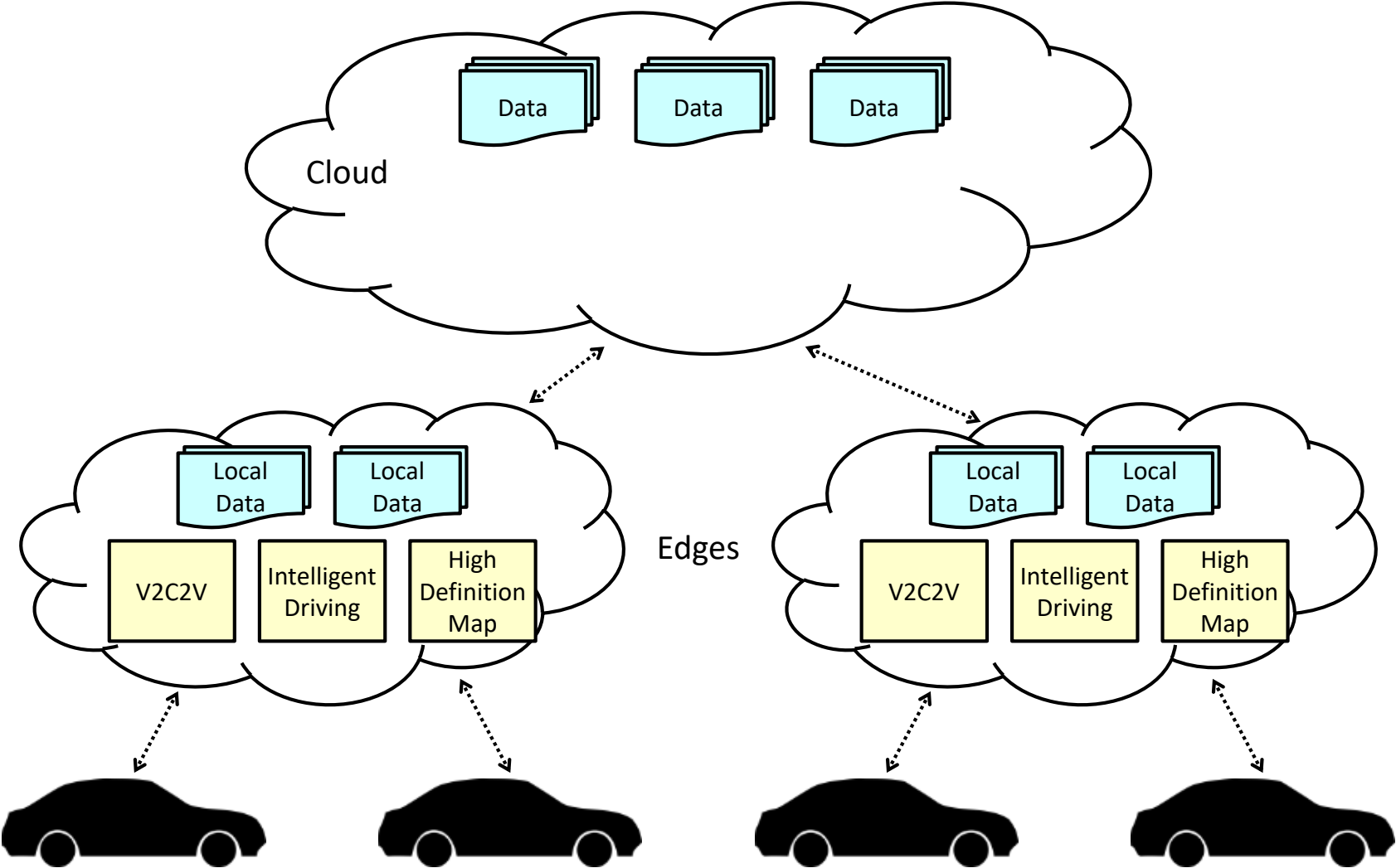
- ❑ Decide task allocation and assign priorities to tasks on ECUs and messages on the network
- ❑ Satisfy timing constraints for tasks, signals, and paths



Edge Computing (1/2)



Edge Computing (2/2)



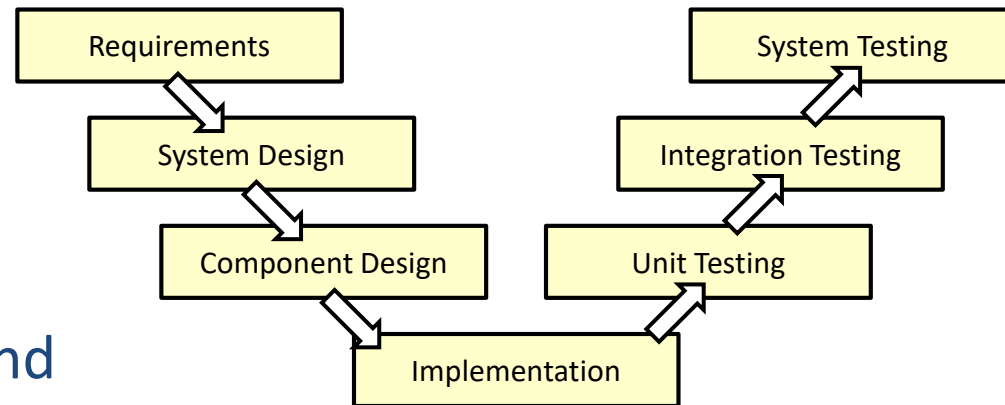
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Motivations

❑ The traditional system development process is the V-model

- An OEM defines the specifications of components
- Suppliers implement those components



❑ Formal verification can be applied to design models and implementations

- However, its scalability limits its applicability to systems of high complexity

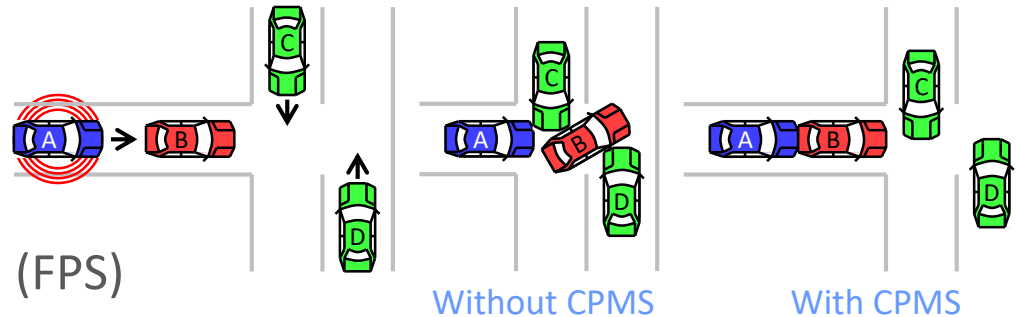
❑ Runtime monitoring becomes a practical alternative

- Detect and notify when there is any specification or requirement violation during runtime

Case Study

Integration of two systems

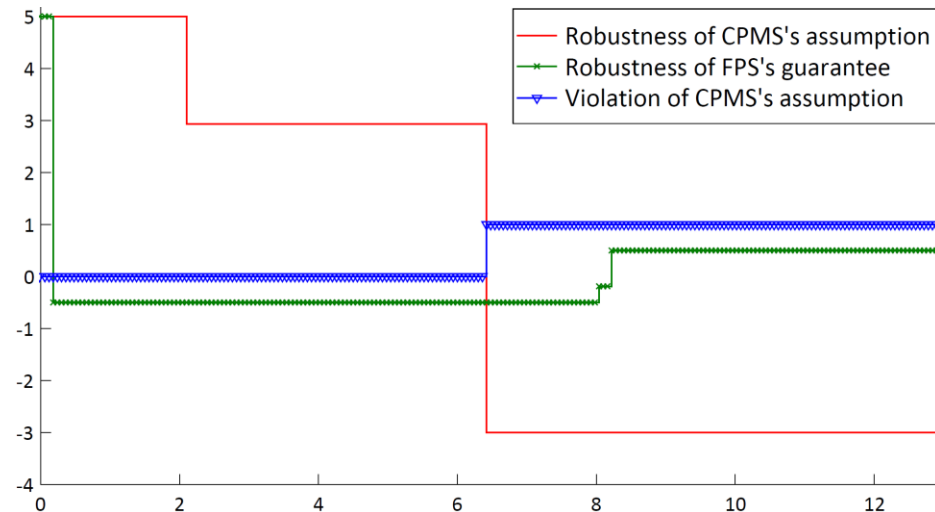
- Cooperative Pile-up Mitigation System (CPMS)
- False-start Prevention System (FPS)



Property specification language and automation tool

- Signal Temporal Logic (STL)
 - Extend Linear Temporal Logic (LTL) to specify properties over real time
- Breach [Donze '10]
 - Given a STL formula, synthesize an online monitor as a C++ program or a MATLAB S-function which can be realized as a Simulink block

An assumption violation of CPMS is detected!



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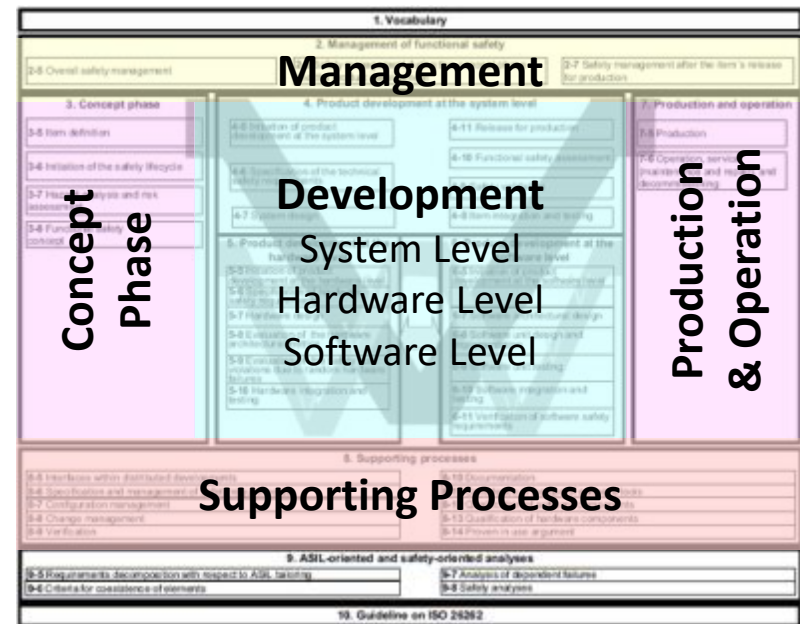
ISO 26262

❑ ISO 26262 is recognized as the state-of-the-art standard for functional safety of automotive systems

❑ Examples

➤ Some software structures are NOT recommended for highest Safety Integrity Level (SIL)

- Dynamic objects and variables
- Multiple uses of variable names
- Implicit type conversions
- Unconditional jumps
- Recursions



Motivations

- ❑ A potential conflict between certification issuers (e.g., OEM) and software suppliers (developers)
 - A certification process represents a systematic way to inspect the source codes
 - Some source codes of software suppliers (developers) are confidential
- ❑ Desired properties
 - Authenticity
 - Only authenticated results from compilers and analysis tools (verification, simulation, and/or testing) are considered by the certification issuers
 - Confidentiality
 - Sensitive source codes of the software suppliers and developers are not released to certification issuers

Certification Protocol

☐ Trusted third-party

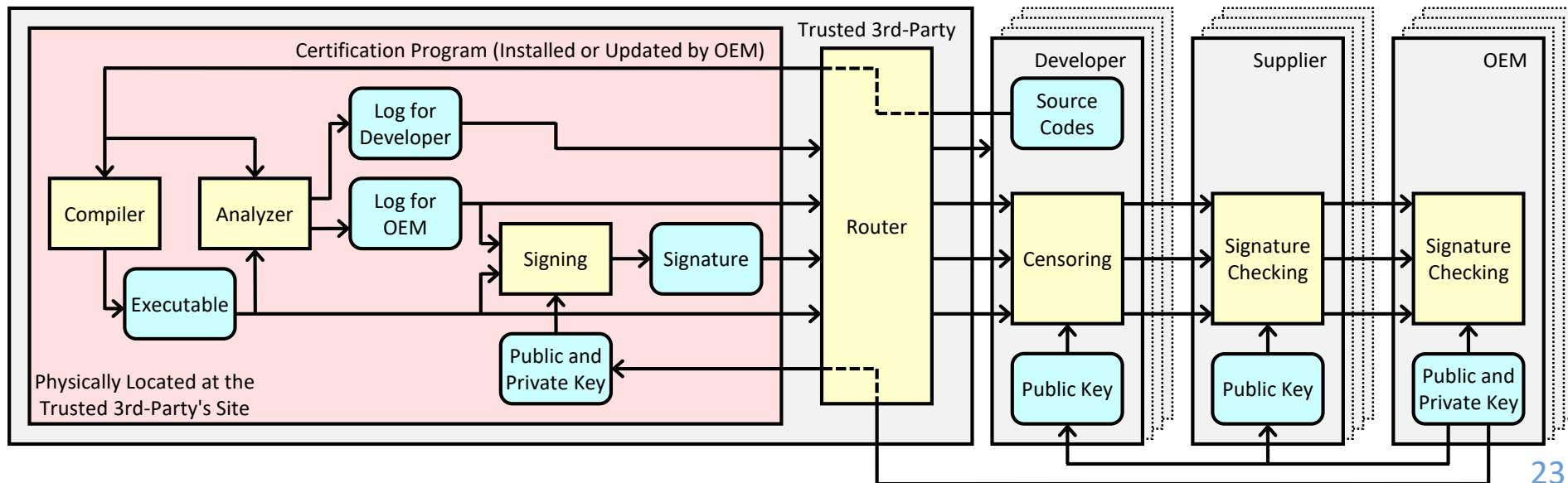
- Run a certification program which consists of a compiler and an analyzer
- Maintain a router which controls the input and the output

☐ Certification program

- All of the compiler, the analyzer, and the private key are updated by the OEM
- The updating process must be unidirectional to guarantee confidentiality

☐ Router

- Only the corresponding developer can be the receiver



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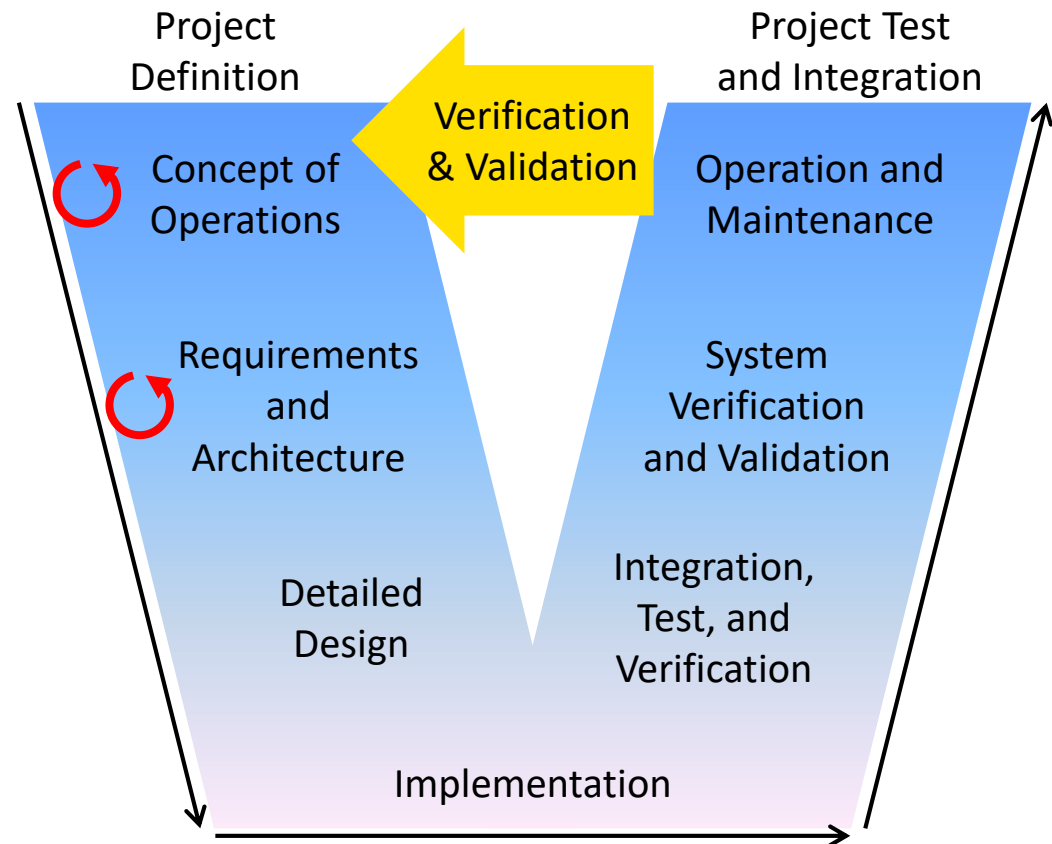
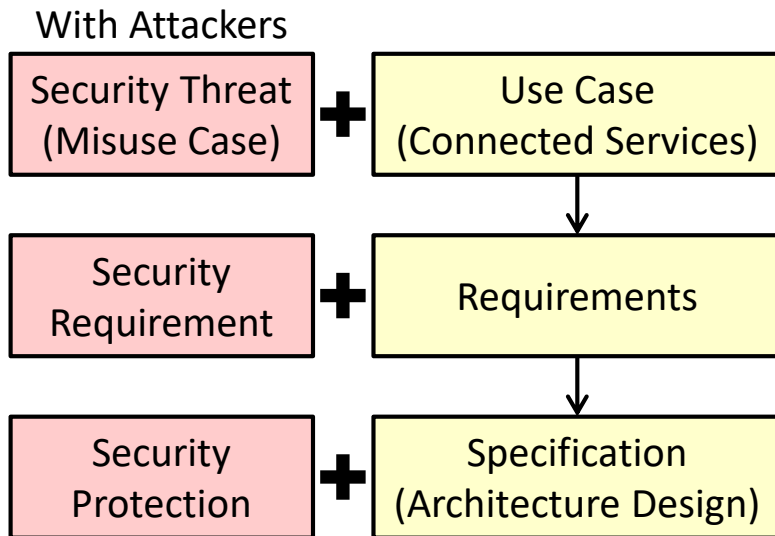
"Design Automation"

- ❑ Consider different design metrics

 - Safety, robustness, performance, security, etc.

- ❑ Assist system designers for early design decisions

 - More efficient process



Security-Aware Design and Analysis

- ❑ Security is a rising concern, especially with connectivity



CBS News, Aug 19, 2014



Live Free or Die Hard (Movie), 2007

- ❑ One hypothetical (but very likely) scenario

- Design stage

- Use the RSA algorithm (strong and famous) for encryption, decryption, and authentication!

- Implementation stage

- Computing units on vehicles cannot afford it... (security mechanisms are usually computation-intensive)

- Result: redesign systems (how can we prevent this?)

Cooperative Adaptive Cruise Control (CACC)

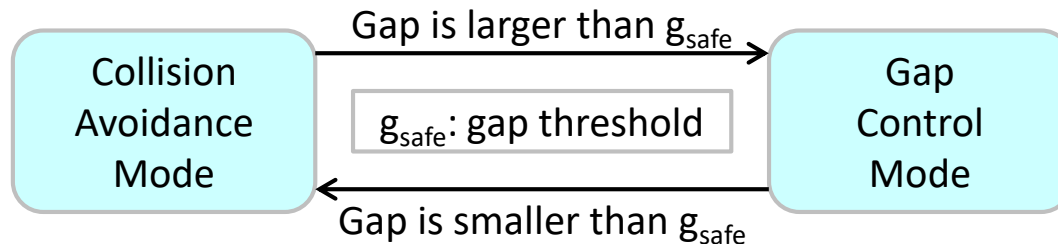
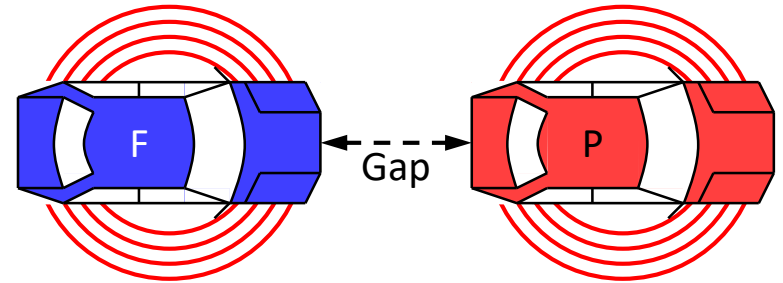
□ Two CACC modes

➤ Gap control mode

- The following vehicle (F) decides acceleration based on the gap, speeds, and accelerations of the two vehicles

➤ Collision avoidance mode

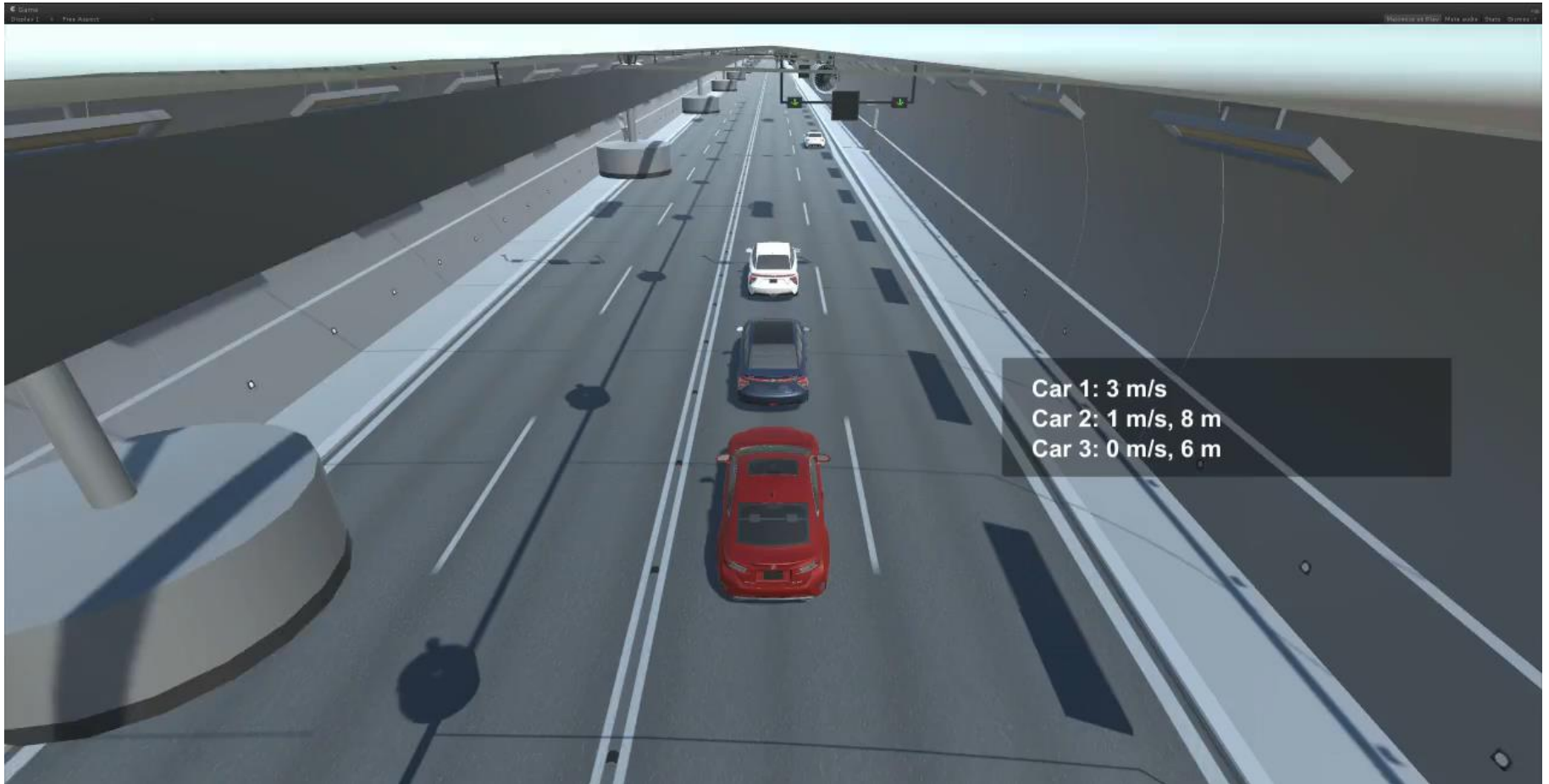
- The following vehicle (F) decelerates with its maximum deceleration



□ Information sources

- Gap and speeds are obtained by sensors
- Accelerations are broadcasted with V2X messages

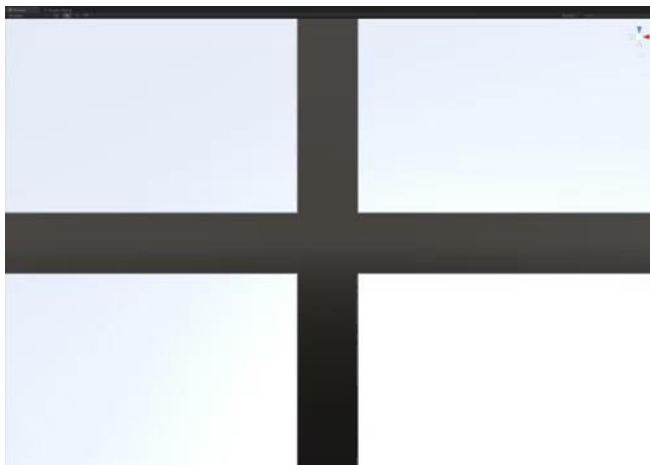
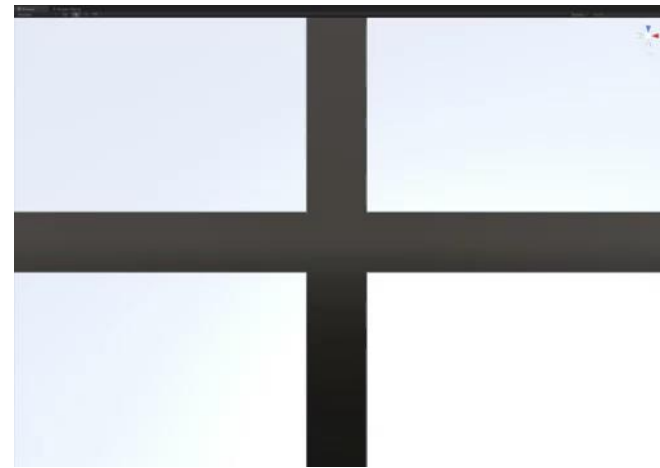
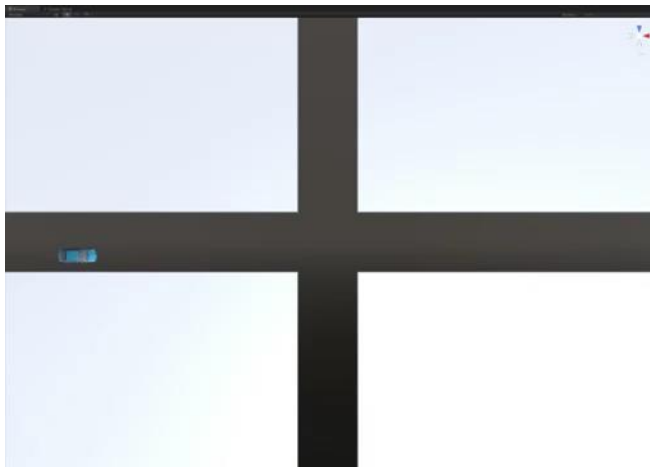
CACC with Jamming or Lying



Intersection Management

(With Jamming or Lying)

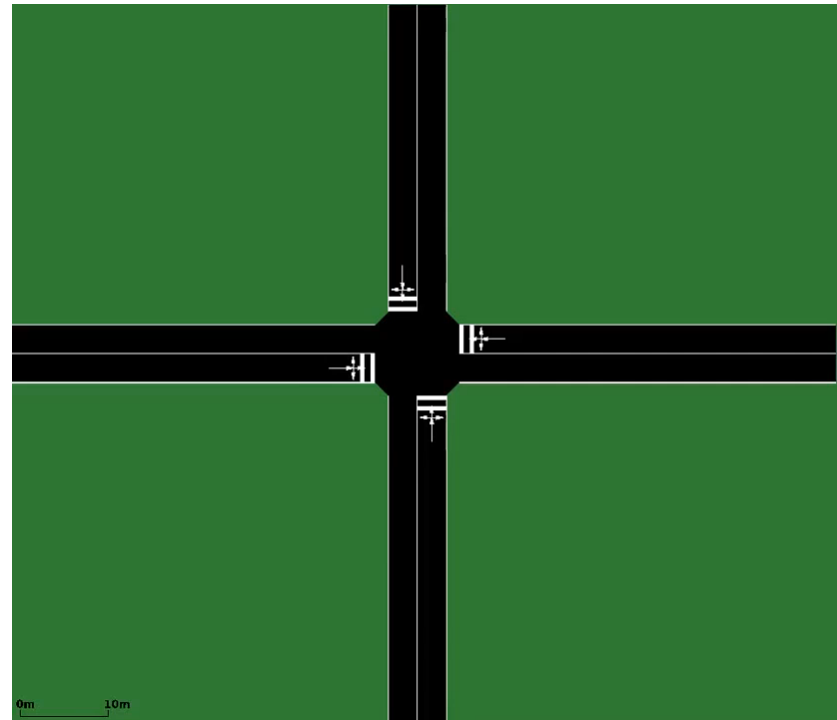
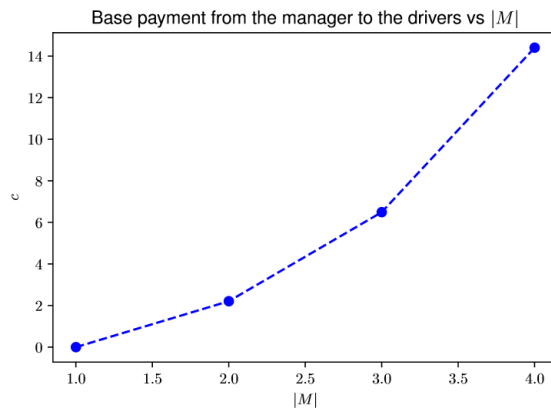
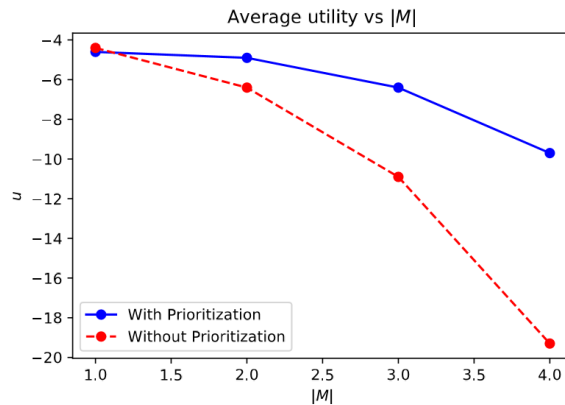
- ❑ An intersection manager receives requests from vehicles, schedule them, and sends confirmations to them



Intersection Management

(Payment-Based Solution against Lying)

- ❑ The payment-based approach supports prioritized intersection management where truthfulness is guaranteed
- ❑ An intersection becomes "more expensive" when there are more cars requesting the intersection



Summary

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Q&A

Thank You!